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Symmetry Breaking and Restoration in the Ginzburg–Landau Model of Nematic Liquid Crystals

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Abstract In this paper we study qualitative properties of global minimizers of the Ginzburg–Landau energy which describes light–matter interaction in the theory of nematic liquid crystals near the Fréedericksz transition. This model depends on two parameters: $\epsilon > 0$ which is small and represents the coherence scale of the system and $a \ge 0$ which represents the intensity of the applied laser light. In particular, we are interested in the phenomenon of symmetry breaking as a and ϵ vary. We show that when a = 0 the global minimizer is radially symmetric and unique and that its symmetry is instantly broken as a > 0 and then restored for sufficiently large values of a. Symmetry breaking is associated with the presence of a new type of topological defect which we named the *shadow vortex*. The symmetry breaking scenario is a rigorous confirmation

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of experimental and numerical results obtained earlier in Barboza et al. (Phys Rev E 93(5):050201, 2016).

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1 Introduction

In a suitable experimental set-up [5–10] involving a liquid crystal sample, a laser and a photoconducting cell, one can observe light defects such as kinks, domain walls and vortices. A concrete example of formation of optical vortices is presented in [7]. To describe this phenomenon starting from the classical Oseen–Frank energy near the Fréedericksz transition, one can reduce the problem to considering the Ginzburg–Landau energy as it was explained in [12]. After some transformations involving scaling to nondimensional variables the latter energy takes form:

$$E(u) = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 - \frac{1}{2\epsilon^2} \mu(x) |u|^2 + \frac{1}{4\epsilon^2} |u|^4 - \frac{a}{\epsilon} f(x) \cdot u, \qquad (1.1)$$

where $u = (u_1, u_2) \in H^1(\mathbb{R}^2, \mathbb{R}^2)$ and $\epsilon > 0$, $a \ge 0$ are real parameters. In the physical context described in [7], the functions μ and f are specific:

$$\mu(x) = e^{-|x|^2} - \chi$$
, with some $\chi \in (0, 1)$, $f(x) = -\frac{1}{2}\nabla\mu(x)$

Physically the order parameter u represents the intensity of light induced by the interaction between the laser beam of Gaussian profile (given by μ) and the nematic liquid crystal sample with the photoconducting cell mounted on top of it. This cell generates electric field whose small, vertical component is described above by f. The parameter a is nondimensional and characterizes the intensity of the laser beam. The two-dimensional model (1.1) shows an excellent agreement with experiments performed with physical parameters near the Fréedericksz transition [7].

All our results hold under more general hypothesis on μ and f which we will state now. We suppose that $\mu \in C^{\infty}(\mathbb{R}^2, \mathbb{R})$ is radial, i.e. $\mu(x) = \mu_{rad}(|x|)$, with $\mu_{rad} \in C^{\infty}(\mathbb{R}, \mathbb{R})$ an even function. We take $f = (f_1, f_2) \in C^{\infty}(\mathbb{R}^2, \mathbb{R}^2)$ also to be radial, i.e. $f(x) = f_{rad}(|x|)\frac{x}{|x|}$, with $f_{rad} \in C^{\infty}(\mathbb{R}, \mathbb{R})$ an odd function. In addition, we assume that

$$\mu \in L^{\infty}(\mathbb{R}^2, \mathbb{R}), \ \mu'_{\text{rad}} < 0 \text{ in } (0, \infty), \text{ and } \mu_{\text{rad}}(\rho) = 0 \text{ for a unique } \rho > 0,$$

$$f \in L^1(\mathbb{R}^2, \mathbb{R}^2) \cap L^{\infty}(\mathbb{R}^2, \mathbb{R}^2), \text{ and } f_{\text{rad}} > 0 \text{ on } (0, \infty).$$

$$(1.2)$$

The Euler–Lagrange equation of E is

$$\epsilon^2 \Delta u + \mu(x)u - |u|^2 u + \epsilon a f(x) = 0, \quad x \in \mathbb{R}^2.$$
(1.3)

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We also write its weak formulation:

$$\int_{\mathbb{R}^2} -\epsilon^2 \sum_{j=1,2} \nabla u_j \cdot \nabla \psi_j + \mu u \cdot \psi - |u|^2 u \cdot \psi + \epsilon a f \cdot \psi = 0,$$

$$\forall \psi \in H^1(\mathbb{R}^2, \mathbb{R}^2), \qquad (1.4)$$

where \cdot denotes the inner product in \mathbb{R}^2 . Note that due to the radial symmetry of μ and f, the energy (1.1) and Eq. (1.3) are invariant under the transformations $v(x) \mapsto g^{-1}v(gx), \forall g \in O(2)$.

Our main purpose in this paper is to study qualitative properties of the global minimizers of *E* as the parameters *a* and ϵ vary. In general, we will assume that $\epsilon > 0$ is small and $a \ge 0$ is bounded uniformly in ϵ . As we will see critical phenomena such as symmetry breaking and restoration, which are the focus of this paper, occur along curves of the form $a = a(\epsilon)$ in the (ϵ, a) plane.

The energy *E* belongs to the class of Ginzburg–Landau type functionals that appear, for example, in the theory of superconductivity or in the theory of Bose–Einstein condensates (see for instance [1,2,4,15–17,23–27] and the references therein). The Gross–Pitaevskii energy functional appearing in the latter theory has form

$$E_{\rm GP}(u) = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 + \frac{1}{2\epsilon^2} V(x) |u|^2 + \frac{1}{4\epsilon} |u|^4 - \Omega x^{\perp} \cdot (iu, \nabla u)$$

subject to $||u||_{L^2} = 1$,

where $\Omega \in \mathbb{R}$ is the angular velocity, $(iu, \nabla u) = iu \nabla \overline{u} - i\overline{u} \nabla u$ and $V(x) = x_1 + \Lambda x_2$ is a harmonic trapping potential (more general nonnegative, smooth *V* are considered as well). The relation between E_{GP} and *E* can be understood if we recast the Gross– Pitaevskii energy taking into account the mass constraint in the form

$$E_{\rm GP}(u) = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 + \frac{1}{4\epsilon^2} \left[\left(|u|^2 - a(x) \right)^2 - \left(a^-(x) \right)^2 \right]^2 - \Omega x^\perp \cdot (iu, \nabla u),$$
(1.5)

where $a(x) = a_0 - V(x)$, a_0 is determined so that $\int_{\mathbb{R}^2} a^+ = 1$ and a^{\pm} are the positive and negative parts of a. The angular velocity has certain threshold values at which different global minimizers appear. When $\Omega = \mathcal{O}(|\ln \epsilon|)$ is below a certain critical value Ω_1 , global minimizers are vortex free [3, 16, 18], while at some other critical values $\Omega_2 > \Omega_1$, global minimizers have at least one vortex [16, 17], which looks locally like the radially symmetric degree ± 1 solution to the Ginzburg–Landau equation (1.9). These localized structures have analogues for the energy functional E: when a = 0, the global minimizer is a vortex free state, and when $a \sim \epsilon |\ln \epsilon|^2$, the global minimizer has one vortex that looks like the standard Ginzburg–Landau vortex [see Fig. 1 (a)]. Possible qualitative difference between the two functionals is manifested in the intermediate region for the values of a. When a satisfies the hypothesis of Theorem 1.2 (ii), the global minimizer has a vortex [see Fig. 1 (c)]. Based on numerical



Fig. 1 a The standard vortex described in Theorem 1.2 (iii), b the standard vortex near the boundary of the set $\mu > 0$ and **c** the shadow vortex described in Theorem 1.2 (ii) in case $a = o(\epsilon | \ln \epsilon |)$. The upper panel shows the global minimizer $v = (v_1, v_2)$ as a vector field in \mathbb{R}^2 . In the lower panel, a radial section of |v| taken at the angle θ indicated in the upper right corner and compared with the Thomas–Fermi limit $\sqrt{\mu^+}$. Numerical simulations were performed after rescaling the original spacial variable $x \mapsto x/\epsilon$

simulations, we conjecture that, rather than coming from the equation (1.9), its rescaled local profile comes from the generalized second Painlevé equation (1.6). We call this new type of defect the shadow vortex (the name is inspired from the physical context, see [12]). Note that the amplitude of the shadow vortex is very small, of order $O(\epsilon^{1/3})$, in contrast with the standard vortex whose amplitude is of order O(1). Numerical simulations show that there exist standard vortex minimizers localized at $|\bar{x}_{\epsilon}| = \rho_0$ strictly between 0 and ρ —this happens when $a \sim \epsilon |\ln \epsilon|$. Despite the similarities between our model and the Gross–Pitaevskii functional it is not clear whether the shadow vortex exists for the Bose–Einstein condensate—proving this is a delicate matter because, unlike the energy of the standard vortex which is of order $|\ln \epsilon|$, the energy of the shadow vortex is relatively small.

The symmetry breaking scenario described above can be seen from another angle since the shadow vortex can be interpreted as a transient vortex state between the homogenous state and the standard vortex state as *a* is increasing. In the Ginzburg–Landau theory of superconductivity, the onset of vortex state is associated with the hysteresis phenomenon near the lower critical field where the energy of the nonvortex state (Meissner solution) equals that of the single vortex state [19]. The difference with the case considered here seems due to the nonsmoothness of the Thomas–Fermi limit and the mediating effect of the solution of the Painlevé equation—in essence it is a boundary layer phenomenon. Still, the results of numerical simulations shown in Fig. 1 suggest that the shadow vortex may exist and be locally stable beyond $a = o(\epsilon | \ln \epsilon |)$ and that the critical value of *a* when the global minimizer becomes the standard vortex

occurs when its energy and that of the shadow vortex are equal. This would point out to the presence of hysteresis also in our case.

In Lemma 2.1, we show that under the above assumptions there exists a global minimizer v of E in $H^1(\mathbb{R}^2, \mathbb{R}^2)$, namely that $E(v) = \min_{H^1(\mathbb{R}^2, \mathbb{R}^2)} E$. In addition, we show that v is a classical solution of (1.3). Some basic properties of the global minimizers are stated in:

Theorem 1.1 Let $v_{\epsilon,a}$ be a global minimizer of E, let $a \ge 0$ be bounded (possibly dependent on ϵ), let $\rho > 0$ be the zero of μ_{rad} and let $\mu_1 := \mu'_{rad}(\rho) < 0$. The following statements hold:

- (i) Let $\Omega \subset D(0; \rho)$ be an open set such that $v_{\epsilon,a} \neq 0$ on Ω , for every $\epsilon \ll 1$. Then $|v_{\epsilon,a}| \rightarrow \sqrt{\mu} \text{ in } C^0_{\text{loc}}(\Omega).$ (ii) For every $\xi = \rho e^{i\theta}$, we consider the local coordinates $s = (s_1, s_2)$ in the basis
- $(e^{i\theta}, ie^{i\theta})$, and the rescaled minimizers:

$$w_{\epsilon,a}(s) = 2^{-1/2} (-\mu_1 \epsilon)^{-1/3} v_{\epsilon,a} \left(\xi + \epsilon^{2/3} \frac{s}{(-\mu_1)^{1/3}} \right).$$

Assuming that $\lim_{\epsilon \to 0} a(\epsilon) = a_0$, then as $\epsilon \to 0$ the function $w_{\epsilon,a}$ converges in $C^2_{loc}(\mathbb{R}^2, \mathbb{R}^2)$ up to subsequence, to a function y bounded in $[s_0, \infty) \times \mathbb{R}$ for every $s_0 \in \mathbb{R}$, which is a minimal solution of

$$\Delta y(s) - s_1 y(s) - 2|y(s)|^2 y(s) - \alpha = 0, \quad \forall s = (s_1, s_2) \in \mathbb{R}^2, \quad (1.6)$$

with $\alpha = \frac{a_0 f(\xi)}{\sqrt{2}\mu_1} \in \mathbb{R}^2$.

(iii) Assuming that $\lim_{\epsilon \to 0} a(\epsilon) = a_0$, then for every $r_0 > \rho$, we have $\lim_{\epsilon \to 0} \frac{v_{\epsilon,a}((r_0+t\epsilon)e^{i\theta})}{\epsilon} = -\frac{a_0}{\mu_{rad}(r_0)}f(r_0e^{i\theta})$ uniformly when t remains bounded and $\theta \in \mathbb{R}$.

Looking at the energy E, it is evident that as $\epsilon \to 0$ the modulus of the global minimizer $|v_{\epsilon,a}|$ should approach a nonnegative root of the polynomial

$$-\mu_{\rm rad}(|x|)y + y^3 - a\epsilon f_{\rm rad}(|x|) = 0,$$

or in other words $|v_{\epsilon,a}| \to \sqrt{\mu^+}$ as $\epsilon \to 0$ in some, perhaps weak, sense. We observe for instance that as a corollary of Theorem 1.1 (i) and Theorem 1.2 (ii) below we obtain when $a = o(\epsilon | \ln \epsilon |)$ the convergence $|v_{\epsilon,a}| \to \sqrt{\mu}$ in $C^0_{\text{loc}}(D(0; \rho))$, thus $\Omega = D(0; \rho)$ in this case. Because of the analogy between the functional E and the Gross-Pitaevskii functional in theory of Bose-Einstein condensates, we will call $\sqrt{\mu^+}$ the Thomas–Fermi limit of the global minimizers (We will comment more on this connection later on.) Theorem 1.1 gives account on how nonsmoothness of the limit of $|v_{\epsilon,a}|$ is mediated near the circumference $|x| = \rho$, where μ changes sign, through the solution of (1.6). This equation is a natural generalization of the second Painlevé equation

$$y'' - sy - 2y^3 - \alpha = 0, \quad s \in \mathbb{R}.$$
 (1.7)

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In [12], we showed that this last equation plays an analogous role in the onedimensional, scalar version of the energy E:

$$E(u,\mathbb{R}) = \int_{\mathbb{R}} \frac{\epsilon}{2} |u_x|^2 - \frac{1}{2\epsilon} \mu(x)u^2 + \frac{1}{4\epsilon} |u|^4 - af(x)u$$

where μ and f are scalar functions satisfying similar hypothesis to those we have described above. In this case, the Thomas–Fermi limit of the global minimizers is simply $\sqrt{\mu^+(x)}$, which is nondifferentiable at the points $x = \pm \xi$ which are the zeros of the even function μ . Near these two points, a rescaled version of the global minimizer approaches a solution of (1.7) similarly as it is described in Theorem 1.1 (ii). It is very important to realize that not every solution of (1.7) can serve as the limit, actually there are only two such solutions: y^+ which is positive, decays to 0 at $+\infty$ and grows like $\sqrt{|s|}$ at $-\infty$ and y^- which is sign changing, has similar asymptotic behaviour at $+\infty$ but $y^-(s) \sim -\sqrt{|s|}$ near $-\infty$. To show existence of y^{\pm} is quite nontrivial, and for proofs we refer to [11,14,29]. Moreover, these two solutions are minimal. To explain what this means, we go back to the present problem since in our case the limiting solutions of (1.6) are necessarily minimal as well. Let

$$E_{\mathrm{P_{II}}}(u, A) = \int_{A} \left[\frac{1}{2} |\nabla u|^{2} + \frac{1}{2} s_{1} |u|^{2} + \frac{1}{2} |u|^{4} + \alpha \cdot u \right].$$

By definition, a solution of (1.6) is minimal if

$$E_{\mathrm{P}_{\mathrm{II}}}(y, \operatorname{supp} \phi) \le E_{\mathrm{P}_{\mathrm{II}}}(y + \phi, \operatorname{supp} \phi) \tag{1.8}$$

for all $\phi \in C_0^{\infty}(\mathbb{R}^2, \mathbb{R}^2)$. This notion of minimality is standard for many problems in which the energy of a localized solution is actually infinite due to noncompactness of the domain. The minimality of the solution of (1.6) arising from the limit in Theorem 1.1 (ii) is a direct consequence of the proof in Sect. 3.

Regarding Theorem 1.1 (iii) we note that since the degree of the local limit of the rescaled global minimizer in $|x| > \rho$ is a function whose topological degree is 1, one may expect that the zero level set of $v_{\epsilon,a}$ is nonempty and that isolated zeros correspond to topological defects which should locally resemble the well-known Ginzburg–Landau vortices. We will show that this is partly true as non-standard vortices occur in the physical regime of parameters.

Before stating our second result we introduce the standard Ginzburg–Landau vortex of degree one which is the radially symmetric solution of

$$\Delta \eta = (|\eta|^2 - 1)\eta, \qquad \eta : \mathbb{R}^2 \to \mathbb{R}^2, \tag{1.9}$$

such that $\eta(x) = \eta_{rad}(|x|) \frac{x}{|x|}$. We say that *u* is a minimal solution of (1.9) if

$$E_{\mathrm{GL}}(u, \operatorname{supp} \phi) \leq E_{\mathrm{GL}}(u + \phi, \operatorname{supp} \phi),$$

for all $\phi \in C_0^{\infty}(\mathbb{R}^2, \mathbb{R}^2)$, where

$$E_{\rm GL}(u, \Omega) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 + \frac{1}{4} (1 - |u|^2)$$

is the Ginzburg–Landau energy associated with (1.9). It is known [28] that any minimal solution of (1.9) is either constant of modulus 1 or has degree ± 1 . Mironescu [20] showed moreover that any minimal solution of (1.9) is either a constant of modulus 1 or (up to orthogonal transformation in the range and translation in the domain) the radial solution η . We also mention some properties of η :

(i) $\eta'_{\text{rad}} > 0 \text{ on } (0, \infty), \eta_{\text{rad}}(0) = 0, \lim_{r \to \infty} \eta_{\text{rad}}(r) = 1,$ (ii) $\int_{\mathbb{R}^2} |\nabla \eta|^2 = \infty.$

Our next theorem shows existence of topological defects of the global minimizers of *E* in several regimes of the parameters (ϵ, a) :

Theorem 1.2 Let $v_{\epsilon,a}$ be a global minimizer. Assume that $a(\epsilon) > 0$, a is bounded and $\lim_{\epsilon \to 0} \epsilon^{1-\frac{3\gamma}{2}} \ln a = 0$ for some $\gamma \in [0, 2/3)$.

(i) For $\epsilon \ll 1$, $v_{\epsilon,a}$ has at least one zero \bar{x}_{ϵ} such that

$$|\bar{x}_{\epsilon}| \le \rho + o(\epsilon^{\gamma}). \tag{1.10}$$

In addition, any sequence of zeros of $v_{\epsilon,a}$, either satisfies (1.10) or it diverges to ∞ .

(ii) For every $\rho_0 \in (0, \rho)$, there exists $b_* > 0$ such that when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|} < b_*$, then any limit point $l \in \mathbb{R}^2$ of the set of zeros of $v_{\epsilon,a}$ satisfies

$$\rho_0 \le |l| \le \rho. \tag{1.11}$$

In addition, if $a = o(\epsilon | \ln \epsilon |)$, then $|l| = \rho$.

(iii) On the other hand, for every $\rho_0 \in (0, \rho)$, there exists $b^* > 0$ such that when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} > b^*$, the set of zeros of $v_{\epsilon,a}$ has a limit point l such that

$$|l| \le \rho_0. \tag{1.12}$$

If $v_{\epsilon,a}(\bar{x}_{\epsilon}) = 0$ and $\bar{x}_{\epsilon} \to l$, then up to a subsequence

$$\lim_{\epsilon \to 0} v_{\epsilon,a}(\bar{x}_{\epsilon} + \epsilon s) \to \sqrt{\mu(l)}(g \circ \eta)(\sqrt{\mu(l)}s),$$

in $C^2_{\text{loc}}(\mathbb{R}^2)$, for some $g \in O(2)$. In addition, if $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} = \infty$ then l = 0.

To discuss physical consequences of this theorem we state:

Theorem 1.3 (i) When a = 0, the global minimizer can be written as $v(x) = (v_{rad}(|x|), 0)$ with $v_{rad} \in C^{\infty}(\mathbb{R})$ positive. It is unique up to change of v by gv with $g \in SO(2)$.

(ii) Given $\epsilon > 0$, there exists A > 0 such that for every a > A, the global minimizer $v_{\epsilon,a}$ is unique and radial, i.e. $v(x) = v_{rad}(|x|)\frac{x}{|x|}$.

Actually radial minimizers such as in Theorem 1.3 (ii) exist for all (ϵ, a) with $\epsilon > 0$ and $a \ge 0$. Indeed, it can be shown that in the class $H^1_{rad}(\mathbb{R}^2, \mathbb{R}^2) := \{u \in H^1(\mathbb{R}^2, \mathbb{R}^2) : gu(x) = u(gx), \forall g \in O(2)\}$ of radial maps (or O(2)-equivariant maps), there exists $u \in H^1_{rad}(\mathbb{R}^2, \mathbb{R}^2)$ such that $E(u) = \min_{H^1_{rad}(\mathbb{R}^2, \mathbb{R}^2)} E$. Existence of the radial minimizer u follows as in the proof of Lemma 2.1, and clearly u is a critical point of E in the subspace $H^1_{rad}(\mathbb{R}^2, \mathbb{R}^2)$. In view of the radial symmetry of μ and f, one can show that the Euler–Lagrange equation (1.4) holds for every $\phi \in H^1(\mathbb{R}^2, \mathbb{R}^2)$ (cf. [21]). As a consequence, $u(x) = u_{rad}(|x|)\frac{x}{|x|}$ is a C^{∞} classical solution of (1.3). In addition, proceeding as in the proof of Theorem 1.3, it is easy to see that the radial minimizer is unique and satisfies $u_{rad} > 0$ on $(0, \infty)$ for every $\epsilon > 0$ and a > 0.

Theorem 1.3 shows that when a = 0 the global minimizer of E inherits the onedimensional radial profile of μ . On the other hand, it would be natural to expect that when a > 0 the forcing term $\epsilon a f$ in (1.3) induces a global minimizer $v \in H^1_{rad}$. Theorem 1.2 shows that this is not the case.

Remark We point out that the hypothesis $\lim_{\epsilon \to 0} \epsilon^{1-\frac{3\gamma}{2}} \ln a = 0$ for some $\gamma \in [0, 2/3)$ was assumed in Theorem 1.2 only to ensure the existence of a sequence of zeros satisfying (1.10). This hypothesis is not needed in the proof of Lemma 3.4 from which the statement (ii) of Theorem 1.2 follows. Therefore, the symmetry of the global minimizers is not radial as soon as $\lim_{\epsilon \to 0} \sup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|} < b_*$, since this condition implies that no limit point of the zeros of the global minimizers belongs to the disc $D(0; \rho_0)$ (cf. Lemma 3.4).

Theorem 1.2 (iii) states further increase in the value of *a* leads to the restoration of the symmetry at least in the limit $\epsilon \rightarrow 0$. Finally, Theorem 1.3 (ii) shows that the symmetry is completely restored provided that *a* is large enough.

This paper is organized as follows: in the next section, we establish existence and basic properties of the global minimizers and in Sect. 3 we prove our theorems.

2 General Results for Minimizers and Solutions

In this section we gather general results for minimizers and solutions that are valid for any values of the parameters $\epsilon > 0$ and $a \ge 0$. We first prove the existence of global minimizers.

Lemma 2.1 For every $\epsilon > 0$ and $a \ge 0$, there exists $v \in H^1(\mathbb{R}^2, \mathbb{R}^2)$ such that $E(v) = \min_{H^1(\mathbb{R}^2, \mathbb{R}^2)} E$. As a consequence, v is a C^{∞} classical solution of (1.3), and moreover $v(x) \to 0$ as $|x| \to \infty$.

Proof We first show that $\inf\{E(u) : u \in H^1(\mathbb{R}^2, \mathbb{R}^2)\} > -\infty$. To see this, we regroup the last three terms in the integral of E(u). Setting $I_{\delta} := \{x \in \mathbb{R}^2 : \mu(x) + \delta > 0\}$, for $\delta > 0$ sufficiently small such that I_{δ} is bounded, we have

$$-\frac{1}{2\epsilon^2}\mu(x)|u|^2 + \frac{1}{8\epsilon^2}|u|^4 < 0 \Longleftrightarrow u^2 < 4\mu \Longrightarrow x \in I_{\delta},$$

thus

$$-\frac{1}{2\epsilon^2}\mu(x)|u|^2 + \frac{1}{8\epsilon^2}|u|^4 \ge -\frac{2}{\epsilon^2} \|\mu\|_{L^{\infty}}^2 \chi_{\delta},$$

where χ_{δ} is the characteristic function of I_{δ} . On the other hand,

$$\frac{1}{8\epsilon^2}|u|^4 - \frac{a}{\epsilon}f(x) \cdot u < 0 \Longrightarrow |u|^3 \le 8a\epsilon|f| \Longrightarrow |fu| \le (8a\epsilon)^{1/3}|f|^{4/3},$$

thus

$$\frac{1}{8\epsilon^2}|u|^4 - \frac{a}{\epsilon}f(x) \cdot u \ge -\frac{8^{1/3}a^{4/3}}{\epsilon^{2/3}}|f|^{4/3}.$$

Next, we notice that $E(u) \in \mathbb{R}$ for every $u \in H^1(\mathbb{R}^2, \mathbb{R}^2)$, thanks to the imbedding $H^1(\mathbb{R}^2) \subset L^p(\mathbb{R}^2)$, for $2 \leq p < \infty$. Now, let $m := \inf_{H^1} E > -\infty$, and let u_n be a sequence such that $E(u_n) \to m$. Repeating the previous computation, we can bound

$$\begin{split} \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u_n|^2 &+ \frac{\delta}{2\epsilon^2} |u_n|^2 = E(u_n) + \int_{\mathbb{R}^2} \frac{1}{2\epsilon^2} (\mu(x) + \delta) |u_n|^2 - \frac{1}{4\epsilon^2} |u_n|^4 \\ &+ \frac{a}{\epsilon} f(x) \cdot u_n \\ &\leq E(u_n) + \frac{2}{\epsilon^2} (\|\mu\|_{L^{\infty}} + \delta)^2 |I_{\delta}| + \frac{8^{1/3} a^{4/3}}{\epsilon^{2/3}} \int_{\mathbb{R}^2} |f|^{4/3}. \end{split}$$

From this expression it follows that $||u_n||_{H^1(\mathbb{R}^2,\mathbb{R}^2)}$ is bounded. As a consequence, for a subsequence still called $u_n, u_n \rightarrow v$ weakly in H^1 , and thanks to a diagonal argument we also have $u_n \rightarrow v$ in L^2_{loc} , and almost everywhere in \mathbb{R}^2 . Finally, by lower semicontinuity

$$\int_{\mathbb{R}^2} |\nabla v|^2 \leq \liminf_{n \to \infty} \int_{\mathbb{R}^2} |\nabla u_n|^2,$$

and by Fatou's Lemma we have

$$\int_{\mathbb{R}^2} |v|^4 \le \liminf_{n \to \infty} \int_{\mathbb{R}^2} |u_n|^4, \text{ and } \int_{\mu \le 0} -\frac{1}{2\epsilon^2} \mu |v|^2 \le \liminf_{n \to \infty} \int_{\mu \le 0} -\frac{1}{2\epsilon^2} \mu |u_n|^2.$$

To conclude, it is clear that

$$\int_{\mu>0} -\frac{1}{2\epsilon^2} \mu |v|^2 = \lim_{n \to \infty} \int_{\mu>0} -\frac{1}{2\epsilon^2} \mu |u_n|^2,$$

thus $m \leq E(v) \leq \liminf_{n \to \infty} E(u_n) = m$. Next, we check that v is bounded. This follows from the fact that there exists a constant M such that for every $x \in \mathbb{R}^2$ and i = 1, 2 the function

$$u_i \to -\frac{1}{2\epsilon^2}\mu(x)|u|^2 + \frac{1}{4\epsilon^2}|u|^4 - \frac{a}{\epsilon}f(x) \cdot u$$

is strictly increasing on $[M, \infty)$ (resp. strictly decreasing on $(\infty, -M]$) independently of the other variable u_j ($j \neq i$, j = 1, 2). Thus, if we truncate a map $u = (u_1, u_2)$ by setting $\tilde{u}_i = \min(M, \max(u_i, -M))$, the truncated map \tilde{u} has smaller energy than u. Clearly the boundedness of v implies by (1.3) the boundedness of Δv and ∇v . In particular, v and $|v|^4$ are uniformly continuous. As a consequence, if $|v(x_n)| > \delta > 0$ for a sequence $|x_n| \to \infty$, then we would have $|v| > \delta/2$ on a ball $B(x_n, r)$ of radius r independent of n, and also $\int_{\mathbb{R}^2} |v|^4 = \infty$, which is impossible. This proves the asymptotic convergence of v to 0.

In the sequel, we will always denote a global minimizer by v. To study the limit of solutions as $\epsilon \to 0$, we need to establish uniform bounds in the different regions considered in Theorem 1.1:

Lemma 2.2 For ϵa belonging to a bounded interval, let $u_{\epsilon,a}$ be a solution of (1.3) converging to 0 as $|x| \to \infty$. Then, the solutions $u_{\epsilon,a}$ and the maps $\epsilon \nabla u_{\epsilon,a}$ are uniformly bounded.

Proof We drop the indexes and write $u := u_{\epsilon,a}$. Since |f|, μ , and ϵa are bounded, the roots of the cubic equation in the variable u_1

$$u_1^3 + (u_2^2 - \mu(x))u_1 - \epsilon a f_1(x) = 0$$

belong to a bounded interval, for all values of x, u_2 , ϵ , a. If u_1 takes positive values, then it attains its maximum $0 \le \max_{\mathbb{R}^2} u_1 = u_1(x_0)$, at a point $x_0 \in \mathbb{R}^2$. In view of (1.3):

$$0 \ge \epsilon^2 \Delta u_1(x_0) = u_1^3(x_0) + (u_2^2(x_0) - \mu(x_0))u_1(x_0) - \epsilon a f_1(x_0),$$

thus it follows that $u_1(x_0)$ is uniformly bounded above. In the same way, we prove the uniform lower bound for u_1 and the uniform bound for u_2 . The boundedness of $\epsilon \nabla u_{\epsilon,a}$ follows from (1.3) and the uniform bound of $u_{\epsilon,a}$.

Lemma 2.3 For $\epsilon \ll 1$ and a belonging to a bounded interval, let $u_{\epsilon,a}$ be a solution of (1.3) converging to 0 as $|x| \to \infty$. Then, there exists a constant K > 0 such that

$$|u_{\epsilon,a}(x)| \le K(\sqrt{\max(\mu(x), 0)} + \epsilon^{1/3}), \quad \forall x \in \mathbb{R}^2.$$
(2.1)

As a consequence, if for every $\xi = \rho e^{i\theta}$, we consider the local coordinates $s = (s_1, s_2)$ in the basis $(e^{i\theta}, ie^{i\theta})$, then the rescaled maps $\tilde{u}_{\epsilon,a}(s) = \frac{u_{\epsilon,a}(\xi+s\epsilon^{2/3})}{\epsilon^{1/3}}$ are uniformly bounded on the half-planes $[s_0, \infty) \times \mathbb{R}$, $\forall s_0 \in \mathbb{R}$.

Proof For the sake of simplicity, we drop the indexes and write $u := u_{\epsilon,a}$. Let us define the following constants

- M > 0 is the uniform bound of $|u_{\epsilon,a}|$ (cf. Lemma 2.2),
- $\lambda > 0$ is such that $3\mu_{rad}(\rho h) \le 2\lambda h, \forall h \in [0, \rho],$
- $F := \sup_{\mathbb{R}^2} |f|,$
- $\kappa > 0$ is such that $\kappa^3 > 3aF$, and $\kappa^4 > 6\lambda$.

Next, we construct the following comparison function

$$\chi(x) = \begin{cases} \lambda \left(\rho - |x| + \frac{\epsilon^{2/3}}{2} \right) & \text{for } |x| \le \rho, \\ \frac{\lambda}{2\epsilon^{2/3}} (|x| - \rho - \epsilon^{2/3})^2 & \text{for } \rho \le |x| \le \rho + \epsilon^{2/3}, \\ 0 & \text{for } |x| \ge \rho + \epsilon^{2/3}. \end{cases}$$
(2.2)

One can check that $\chi \in C^1(\mathbb{R}^2 \setminus \{0\}) \cap H^1(\mathbb{R}^2)$ satisfies $\Delta \chi \leq \frac{2\lambda}{c^{2/3}}$ in $H^1(\mathbb{R}^2)$. Finally, we define the function $\psi := \frac{|u|^2}{2} - \chi - \kappa^2 \epsilon^{2/3}$ and compute:

$$\epsilon^{2} \Delta \psi = \epsilon^{2} (|\nabla u|^{2} + u \cdot \Delta u - \Delta \chi)$$

$$\geq -\mu |u|^{2} + |u|^{4} - \epsilon a f \cdot u - \epsilon^{2} \Delta \chi$$

$$\geq -\mu |u|^{2} + |u|^{4} - \epsilon a F |u| - 2\epsilon^{4/3} \lambda.$$
(2.3)

Now, one can see that when $x \in \Omega := \{x \in \mathbb{R}^2 : \psi(x) > 0\}$, we have $\frac{|u|^4}{3} - \mu |u|^2 \ge 0$, since

$$x \in \Omega \cap \overline{D(0;\rho)} \Rightarrow \frac{|u|^4}{3} \ge \frac{2\lambda}{3} \left(\rho - |x| + \frac{\epsilon^{2/3}}{2}\right) |u|^2 \ge \mu |u|^2.$$

On the open set Ω , we also have: $\frac{|u|^4}{3} \ge \frac{\kappa^4}{3}\epsilon^{4/3} \ge 2\epsilon^{4/3}\lambda$, and $\frac{|u|^4}{3} \ge \frac{\kappa^3}{3}\epsilon|u| \ge \epsilon aF|u|$. Thus $\Delta \psi \ge 0$ on Ω in the H^1 sense. To conclude, we apply Kato's inequality that gives: $\Delta \psi^+ \ge 0$ on \mathbb{R}^2 in the H^1 sense. Since ψ^+ is subharmonic with compact support, we obtain by the maximum principle that $\psi^+ \equiv 0$ or equivalently $\psi \leq 0$ on \mathbb{R}^2 . The statement of the lemma follows by adjusting the constant K.

Lemma 2.4 Assume that a is bounded and let $u_{\epsilon,a}$ be solutions of (1.3) uniformly bounded. Then, the maps $\frac{u_{\epsilon,a}}{\epsilon}$ and $\nabla u_{\epsilon,a}$ are uniformly bounded on the sets $\{x : |x| \ge \epsilon\}$ ρ_1 for every $\rho_1 > \rho$.

Proof We consider the sets $S := \{x : |x| \ge \rho_1\} \subset S' := \{x : |x| > \rho'_1\}$, with $\rho < \rho'_1 < \rho_1$, and define the constants:

- M > 0 which is the uniform bound of $|u_{\epsilon,a}|$,
- $\mu_0 = -\mu_{rad}(\rho'_1) > 0$,
- $f_{\infty} = \|f\|_{L^{\infty}}$,
- $a^* := \sup_{k \to 0} a(\epsilon),$ $k = \frac{2a_* f_{\infty}}{\mu_0} > 0.$

Next, we introduce the function $\psi(x) = \frac{1}{2}(|u|^2 - k^2\epsilon^2)$ satisfying:

$$\epsilon^{2} \Delta \psi = \epsilon^{2} \Delta \frac{|u|^{2}}{2} \ge |u|^{4} + \mu_{0}|u|^{2} - \epsilon a_{*} f_{\infty}|u|, \forall x \in S',$$
$$\ge \mu_{0} \psi, \forall x \in S' \text{ such that } \psi(x) \ge 0.$$

By Kato's inequality, we have $\epsilon^2 \Delta \psi^+ \ge \mu_0 \psi^+$ on *S'*, in the H^1 sense, and utilizing a standard comparison argument, we deduce that $\psi^+(x) \le M^2 e^{-\frac{c}{\epsilon} d(x, \partial S')}$, $\forall x \in S$, and $\forall \epsilon \ll 1$, where *d* stands for the Euclidean distance, and c > 0 is a constant. It is clear that

$$d(x, \partial S') > -\frac{\epsilon}{c} \ln\left(\frac{k^2 \epsilon^2}{2M^2}\right) \Rightarrow M^2 e^{-\frac{c}{\epsilon} d(x, \partial S')} < \frac{k^2 \epsilon^2}{2} \Rightarrow |u|^2 < 2k^2 \epsilon^2.$$

Therefore, there exists ϵ_0 such that

$$\frac{|u_{\epsilon,a}(x)|}{\epsilon} \le \sqrt{2}k, \ \forall \epsilon < \epsilon_0, \ \forall x \in S.$$
(2.4)

The boundedness of $\nabla u_{\epsilon,a}$ follows from (1.3) and the uniform bound (2.4).

3 Proof of Theorems 1.1, 1.2 and 1.3

Proof of Theorem 1.1 (*i*) Suppose by contradiction that |v| does not converge uniformly to $\sqrt{\mu}$ on a closed set $F \subset \Omega$. Then, there exist a sequence $\epsilon_n \to 0$ and a sequence $\{x_n\} \subset F$ such that

either
$$|v_{\epsilon_n}(x_n)| \ge \sqrt{\mu(x_n)} + \delta$$
 or $|v_{\epsilon_n}(x_n)| \le \sqrt{\mu(x_n)} - \delta$, for some $\delta > 0$. (3.1)

In addition, we may assume that up to a subsequence $\lim_{n\to\infty} x_n = x_0 \in F$. Next, we consider the rescaled maps $\tilde{v}_n(s) = v_{\epsilon_n}(x_n + \epsilon_n s)$ that satisfy

$$\Delta \tilde{v}(s) + \mu (x_n + \epsilon_n s) \tilde{v}(s) - |\tilde{v}(s)|^2 \tilde{v}(s) + \epsilon_n a f(x_n + \epsilon_n s) = 0, \ \forall s \in \mathbb{R}^2.$$
(3.2)

In view of the Lemma 2.2 and (3.2), \tilde{v}_n and its first derivatives are uniformly bounded for $\epsilon \ll 1$. Moreover, by differentiating (3.2), one also obtains the boundedness of the second derivatives of \tilde{v}_n on compact sets. Thus, we can apply the theorem of Ascoli via a diagonal argument and show that for a subsequence still called \tilde{v}_n , \tilde{v}_n converges in $C^2_{\text{loc}}(\mathbb{R}^2, \mathbb{R}^2)$ to a map \tilde{V} , that we are now going to determine. For this purpose, we introduce the rescaled energy

$$\tilde{E}(\tilde{u}) = \int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \tilde{u}(s)|^2 - \frac{1}{2} \mu(x_n + \epsilon_n s) |\tilde{u}(s)|^2 + \frac{1}{4} |\tilde{u}(s)|^4 - \epsilon_n a f(x_n + \epsilon_n s) \cdot \tilde{u}(s) \right) ds = E(u),$$

where we have set $\tilde{u}(s) = u_{\epsilon_n}(x_n + \epsilon_n s)$, i.e. $u_{\epsilon_n}(x) = \tilde{u}\left(\frac{x-x_n}{\epsilon_n}\right)$. Let $\tilde{\xi}$ be a test function with support in the compact set *K*. We have $\tilde{E}(\tilde{v}_n + \tilde{\xi}, K) \ge \tilde{E}(\tilde{v}_n, K)$, and at the limit $G_0(\tilde{V} + \tilde{\xi}, K) \ge G_0(\tilde{V}, K)$, where

$$G_0(\psi, K) = \int_K \left[\frac{1}{2} |\nabla \psi|^2 - \frac{1}{2} \mu(x_0) |\psi|^2 + \frac{1}{4} |\psi|^4 \right],$$

or equivalently $G(\tilde{V} + \tilde{\xi}, K) \ge G(\tilde{V}, K)$, where

$$G(\psi, K) = \int_{K} \left[\frac{1}{2} |\nabla \psi|^{2} - \frac{1}{2} \mu(x_{0}) |\psi|^{2} + \frac{1}{4} |\psi|^{4} + \frac{(\mu(x_{0}))^{2}}{4} \right]$$
$$= \int_{K} \left[\frac{1}{2} |\nabla \psi|^{2} + \frac{1}{4} (|\psi|^{2} - \mu(x_{0}))^{2} \right].$$
(3.3)

Thus, we deduce that \tilde{V} is a bounded minimal solution of the P.D.E. associated with the functional (3.3):

$$\Delta \tilde{V}(s) + (\mu(x_0) - |\tilde{V}(s)|^2)\tilde{V}(s) = 0.$$
(3.4)

If \tilde{V} is a constant of modulus $\sqrt{\mu(x_0)}$, then we have $\lim_{n\to\infty} |v_{\epsilon_n}(x_n)| = \sqrt{\mu(x_0)}$ which is excluded by (3.1). Therefore, we obtain (up to orthogonal transformation in the range) $\tilde{V}(s) = \sqrt{\mu(x_0)} \eta(\sqrt{\mu(x_0)}(s-s_0))$, where $\eta(s) = \eta_{rad}(|s|)\frac{s}{|s|}$ is the radial solution to the Ginzburg–Landau equation (1.9), and $s_0 \in \mathbb{R}^2$. In particular, the degree of \tilde{V} on $\partial D(0; 2|s_0|)$ is ± 1 , and by the $C^1_{loc}(\mathbb{R}^2, \mathbb{R}^2)$ convergence, we deduce that for $\epsilon_n \ll 1$ the degree of \tilde{v}_n is still ± 1 on $\partial D(0; 2|s_0|)$. This implies that v_n has a zero in $D(x_n; 2\epsilon_n|s_0|)$ for $\epsilon_n \ll 1$, which contradicts the fact that $v_{\epsilon} \neq 0$ on Ω for $\epsilon \ll 1$. \Box

Proof Theorem 1.1 (*ii*) For every $\xi = \rho e^{i\theta}$, we consider the local coordinates $s = (s_1, s_2)$ in the basis $(e^{i\theta}, ie^{i\theta})$, and we rescale the global minimizers v as in Lemma 2.3 by setting $\tilde{v}_{\epsilon,a}(s) = \frac{v_{\epsilon,a}(\xi + s\epsilon^{2/3})}{\epsilon^{1/3}}$. Clearly $\Delta v(s) = \epsilon \Delta v(\xi + s\epsilon^{2/3})$, thus,

$$\Delta \tilde{v}(s) + \frac{\mu(\xi + s\epsilon^{2/3})}{\epsilon^{2/3}}\tilde{v}(s) - |\tilde{v}^2(s)|\tilde{v}(s) + af(\xi + s\epsilon^{2/3}) = 0, \quad \forall s \in \mathbb{R}^2.$$

Writing $\mu(\xi + h) = \mu_1 h_1 + h \cdot A(h)$, with $\mu_1 := \mu'_{rad}(\rho) < 0, A \in C^{\infty}(\mathbb{R}^2, \mathbb{R}^2)$, and A(0) = 0, we obtain

$$\Delta \tilde{v}(s) + (\mu_1 s_1 + A(s\epsilon^{2/3}) \cdot s)\tilde{v}(s) - |\tilde{v}^2(s)|\tilde{v}(s) + af(\xi + s\epsilon^{2/3}) = 0, \quad \forall s \in \mathbb{R}^2.$$
(3.5)

Next, we define the rescaled energy by

$$\tilde{E}(\tilde{u}) = \int_{\mathbb{R}} \left(\frac{1}{2} |\nabla \tilde{u}(s)|^2 - \frac{\mu(\xi + s\epsilon^{2/3})}{2\epsilon^{2/3}} \tilde{u}^2(s) + \frac{1}{4} |\tilde{u}|^4(s) - af(\xi + s\epsilon^{2/3}) \cdot \tilde{u}(s) \right) \mathrm{d}s.$$
(3.6)

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With this definition $\tilde{E}(\tilde{u}) = \frac{1}{\epsilon^{2/3}} E(u)$. From Lemma 2.3 and (3.5), it follows that $\Delta \tilde{v}$ and also $\nabla \tilde{v}$ are uniformly bounded on compact sets. Moreover, by differentiating (3.5) we also obtain the boundedness of the second derivatives of \tilde{v} . Thanks to these uniform bounds, we can apply the theorem of Ascoli via a diagonal argument to obtain the convergence of \tilde{v} in $C_{\text{loc}}^2(\mathbb{R}^2, \mathbb{R}^2)$ (up to a subsequence) to a minimal solution [cf. (1.8)] \tilde{V} of the P.D.E.

$$\Delta \tilde{V}(s) + \mu_1 s_1 \tilde{V}(s) - |\tilde{V}|^2(s) \tilde{V}(s) + a_0 f(\xi) = 0, \forall s \in \mathbb{R}^2, \text{ with } a_0 := \lim_{\epsilon \to 0} a(\epsilon),$$
(3.7)

which is associated with the functional

$$\tilde{E}_{0}(\phi, J) = \int_{J} \left(\frac{1}{2} |\nabla \phi(s)|^{2} - \frac{\mu_{1}}{2} s_{1} |\phi|^{2}(s) + \frac{1}{4} |\phi|^{4}(s) - a_{0} f(\xi) \cdot \phi(s) \right) \mathrm{d}s.$$
(3.8)

Setting $y(s) := \frac{1}{\sqrt{2}(-\mu_1)^{1/3}} \tilde{V}\left(\frac{s}{(-\mu_1)^{1/3}}\right)$, (3.7) reduces to (1.6) with $\alpha = \frac{a_0 f(\xi)}{\sqrt{2}\mu_1}$, and y is still a minimal solution of (1.6). In addition, by Lemma 2.1, \tilde{V} and y are bounded in the half-planes $[s_0, \infty) \times \mathbb{R}, \forall s_0 \in \mathbb{R}$.

Proof of Theorem 1.1 (*iii*) For every $x_0 = r_0 e^{i\theta_0}$ fixed, with $r_0 > \rho$, we consider the local coordinates $s = (s_1, s_2)$ in the basis $(e^{i\theta_0}, ie^{i\theta_0})$, and the rescaled maps $\tilde{v}_{\epsilon,a}(s) = \frac{v_{\epsilon,a}(x_0+\epsilon s)}{\epsilon}$, satisfying

$$\Delta \tilde{v}(s) + \mu(x_0 + \epsilon s)\tilde{v}(s) - \epsilon^2 |\tilde{v}(s)|^2 \tilde{v}(s) + af(x_0 + \epsilon s) = 0, \ \forall s \in \mathbb{R}^2.$$
(3.9)

In view of the bound (2.4) provided by Lemma 2.3 and (3.9), we can see that the first derivatives of $\tilde{v}_{\epsilon,a}$ are uniformly bounded on compact sets for $\epsilon \ll 1$. Moreover, by differentiating (3.9), one can also obtain the boundedness of the second derivatives of \tilde{v} on compact sets. As a consequence, we conclude that $\lim_{\epsilon \to 0, a \to a_0} \tilde{v}_{\epsilon,a}(s) = \tilde{V}(s)$ in C_{loc}^2 , where $\tilde{V}(s) \equiv -\frac{a_0}{\mu_{\text{rad}}(r_0)} f(r_0 e^{i\theta_0})$ is the unique bounded solution of

$$\Delta \tilde{V}(s) + \mu(x_0)\tilde{V}(s) + a_0 f(x_0) = 0, \ \forall s \in \mathbb{R}^2.$$
(3.10)

Indeed, consider a smooth and bounded solution $u : \mathbb{R}^2 \to \mathbb{R}^2$ of $\Delta u = \nabla W(u)$ where the potential $W : \mathbb{R}^2 \to \mathbb{R}$ is smooth and strictly convex. Then, we have $\Delta(W(u)) =$ $|\nabla W(u)|^2 + \sum_{i=1}^2 D^2 W(u)(u_{x_i}, u_{x_i}) \ge 0$, and since W(u) is bounded we deduce that W(u) is constant. Therefore, $u \equiv u_0$ where $u_0 \in \mathbb{R}^2$ is such that $\nabla W(u_0) = 0$. Finally, the uniform convergence $\lim_{\epsilon \to 0, a \to a_0} \frac{u_{\epsilon,a}((r_0 + t\epsilon)e^{i\theta})}{\epsilon} = -\frac{a_0}{\mu_{rad}(r_0)} f(r_0e^{i\theta})$, when *t* remains bounded and $\theta \in \mathbb{R}$, follows from the invariance of equation (1.3) under the transformations $u(x) \mapsto g^{-1}u(gx), \forall g \in SO(2)$.

Proof of Theorem 1.2 (*i*) The proof follows from the next lemma which applies in the more general case of uniformly bounded solutions: \Box

Lemma 3.1 Consider the annulus $A = \{\rho + \tau \epsilon^{\gamma} \le |x| \le \rho_1\}$ with $\rho_1 > \rho, \tau > 0$ and $\gamma \in [0, 2/3)$ fixed. Assume that $a(\epsilon) > 0$ and $\lim_{\epsilon \to 0} \epsilon^{1-\frac{3\gamma}{2}} \ln(a) = 0$, and let $u_{\epsilon,a}$ be solutions of (1.3) uniformly bounded. Then, there exists ϵ_0 such that $u_{\epsilon,a}(x) \ne 0$, $\forall x \in A, \forall \epsilon < \epsilon_0$. In addition,

- $\lim_{\epsilon \to 0} \frac{u_{\epsilon,a}(x)}{|u_{\epsilon,a}(x)|} = \frac{x}{|x|}$, uniformly on A,
- when $\epsilon \ll 1$, the solution $u_{\epsilon,a}$ has at least one zero \bar{x}_{ϵ} in the open disc $|x| < \rho + \tau \epsilon^{\gamma}$.

Proof We examine the sign of the projections $u_{\nu}(x) = -(u(x) \cdot \nu)$, where $\nu = (\cos \theta_0, \sin \theta_0)$ is a unit vector. Consider for every $\delta > 0$ the set

$$S_{\delta} := \left\{ x = re^{i\theta} : \rho + \tau \epsilon^{\gamma} \le r \le \rho_1, -\frac{\pi}{2} + \delta + \theta_0 \le \theta \le \frac{\pi}{2} - \delta + \theta_0 \right\},\$$

which is contained in the domain

$$S'_{\delta} := \left\{ x = re^{i\theta} : \ \rho + \frac{\tau}{2}\epsilon^{\gamma} < r < \rho_2, \ -\frac{\pi}{2} + \frac{\delta}{2} + \theta_0 < \theta < \frac{\pi}{2} - \frac{\delta}{2} + \theta_0 \right\},$$

with $\rho_1 < \rho_2$. In view of (1.2), let $0 < f_{\delta} := \cos(\frac{\pi - \delta}{2}) \min_{r \in [\rho, \rho_2]} f_{rad}(r) \le \inf_{x \in S'_{\delta}} (f(x) \cdot \nu)$, and notice that

$$\epsilon^2 \Delta u_{\nu} \ge (|u|^2 - \mu)u_{\nu} + \epsilon a f_{\delta}, \ \forall x \in S'_{\delta}.$$

Next, we define:

- M > 0 which is the uniform bound of $|u_{\epsilon,a}|$,
- $\mu_0 > 0$ such that $2\mu_0 h \le -\mu_{rad}(\rho + h)$, for $h \in [0, 1]$,
- $\mu_{\infty} = \sup_{\mathbb{R}^2} (-\mu) > 0$,
- $k_{\epsilon} = \frac{af_{\delta}}{M^2 + \mu_{\infty}} > 0,$

and the function $\psi(x) = u_{\nu} + k_{\epsilon}\epsilon$. One can check that when $x \in \Omega := \{x \in S'_{\delta} : \psi(x) > 0\}$, we have $\epsilon^2 \Delta \psi \ge \tau \epsilon^{\gamma} \mu_0 \psi$ on Ω . To extend the previous inequality to the domain S'_{δ} , we apply Kato's inequality that gives: $\epsilon^{2-\gamma} \Delta \psi^+ \ge \tau \mu_0 \psi^+$ on S'_{δ} , in the H^1 sense. Now, since in $\gamma \in [0, 2/3)$, we can see that $\forall x \in S_{\delta} : d(x, \partial S'_{\delta}) \ge \kappa \epsilon^{\gamma} \gg \epsilon^{1-\frac{\gamma}{2}}$ for some constant $\kappa > 0$, where *d* stands for the Euclidean distance, and utilizing a standard comparison argument, we deduce that $\psi^+(x) \le (M + k_{\epsilon}\epsilon)e^{-\frac{c}{\epsilon^{1-\frac{\gamma}{2}}}d(x,\partial S'_{\delta})}$, $\forall x \in S_{\delta}, \forall \epsilon \ll 1$, where c > 0 is a constant. Finally, in view of $\lim_{\epsilon \to 0} \epsilon^{1-\frac{3\gamma}{2}} \ln(a) = 0$ and $\gamma \in [0, 2/3)$, there exists ϵ_{δ} (independent of θ_0) such that

$$\forall \epsilon < \epsilon_{\delta}, \ \forall x \in S_{\delta} : \ d(x, \partial S'_{\delta}) > -\frac{\epsilon^{1-\frac{\gamma}{2}}}{c} \ln\left(\frac{k_{\epsilon}\epsilon}{M+k_{\epsilon}\epsilon}\right) \Rightarrow \psi^{+}(x)$$

$$\leq (M+k_{\epsilon}\epsilon)e^{-\frac{c}{\epsilon^{1-\frac{\gamma}{2}}}d(x, \partial S'_{\delta})} < k_{\epsilon}\epsilon.$$

$$(3.11)$$

From this it follows $u_{\nu}(x) < 0$ hence $u(x) \cdot \nu > 0$

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To conclude, we notice that every $x = re^{i\theta} \in A$ belongs to the intersection of the sets S_{δ} corresponding to the angles $\theta_0 \in [\theta - \frac{\pi}{2} + \delta, \theta + \frac{\pi}{2} - \delta]$. As a consequence, $\forall x = re^{i\theta} \in A, \forall \epsilon < \epsilon_{\delta}, \forall \theta_0 \in [\theta - \frac{\pi}{2} + \delta, \theta + \frac{\pi}{2} - \delta]$, we have $u(x) \cdot (\cos \theta_0, \sin \theta_0) > 0$, and in particular

- $u(x) \neq 0$,
- $u(x) = |u(x)|e^{i(\phi+\theta)}$, with $\phi \in (-\delta, \delta)$.

Since for every $\delta > 0$ arbitrary small, we can find an $\epsilon_{\delta} > 0$ such that $\left| \frac{u(x)}{|u(x)|} - \frac{x}{|x|} \right| \le |e^{i\phi} - 1|$ holds $\forall x \in A, \forall \epsilon < \epsilon_{\delta}$, with $\phi \in (-\delta, \delta)$, it follows that $\lim_{\epsilon \to 0} \frac{u_{\epsilon,a}(x)}{|u_{\epsilon,a}(x)|} = \frac{x}{|x|}$, uniformly on A. In addition, for $\epsilon < \epsilon_{\delta}$ (with δ small), the winding number of u on the circle $|x| = \rho + \tau \epsilon^{\gamma}$ is one. Thus by degree theory, the solution u has at least one zero in the open disc $|x| < \rho + \tau \epsilon^{\gamma}$.

Theorem 1.2 (ii) The minimum of the energy defined in (1.1) is nonpositive and tends to $-\infty$ as $\epsilon \to 0$. Since we are interested in the behaviour of the minimizers as $\epsilon \to 0$, it is useful to define a renormalized energy, which is obtained by adding to (1.1) a suitable term so that the result is tightly bounded from above. We define the renormalized energy as

$$\mathcal{E}(u) := E(u) + \int_{|x| < \rho} \frac{\mu^2}{4\epsilon^2} = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 + \int_{|x| < \rho} \frac{(|u|^2 - \mu)^2}{4\epsilon^2} + \int_{|x| > \rho} \frac{|u|^2 (|u|^2 - 2\mu)}{4\epsilon^2} - \frac{a}{\epsilon} \int_{\mathbb{R}^2} f \cdot u, \quad (3.12)$$

and claim the bound:

Lemma 3.2

$$\mathcal{E}(v_{\epsilon,a}) \le \frac{\pi |\mu_1|\rho}{6} |\ln \epsilon| + \mathcal{O}(1) \text{ for } \epsilon \ll 1 \text{ and arbitrary } a, \qquad (3.13)$$

where $\mu_1 = \mu'_{rad}(\rho)$.

Proof Let us consider the C^1 piecewise map $\psi = (\psi_1, \psi_2)$:

$$\psi_1(x) = \begin{cases} \sqrt{\mu(x)} & \text{for } |x| \le \rho - \epsilon^{2/3} \\ k_\epsilon \epsilon^{-1/3}(\rho - |x|) & \text{for } \rho - \epsilon^{2/3} \le |x| \le \rho \\ 0 & \text{for } |x| \ge \rho \end{cases}, \quad \psi_2(x) = 0,$$

with k_{ϵ} defined by $k_{\epsilon}\epsilon^{1/3} = \sqrt{\mu_{rad}(\rho - \epsilon^{2/3})} \implies k_{\epsilon} = \mathcal{O}(1)$. Since $\psi \in H^1(\mathbb{R}^2, \mathbb{R}^2)$, it is clear that $\mathcal{E}(v) \leq \mathcal{E}(\psi)$. We check that $\mathcal{E}(\psi) = \frac{\pi |\mu_1|\rho}{6} |\ln \epsilon| + \mathcal{O}(1)$, since it is the sum of the following integrals:

$$\begin{split} &\int_{\rho-\epsilon^{2/3}<|x|<\rho} \frac{(|\psi|^2-\mu)^2}{4\epsilon^2} = \mathcal{O}(1), \int_{|x|>\rho-\epsilon^{2/3}} \frac{1}{2} |\nabla\psi_1|^2 = \mathcal{O}(1), \\ &\int_{|x|\le\rho-\epsilon^{2/3}} \frac{1}{2} \frac{|\mu'_{\rm rad}(|x|)|^2}{4\mu} = \frac{|\mu_1|}{8} \int_{|x|\le\rho-\epsilon^{2/3}} \frac{1}{\rho-|x|} \\ &+ \mathcal{O}(1) = \frac{\pi |\mu_1|\rho}{6} |\ln\epsilon| + \mathcal{O}(1). \end{split}$$

We also compute a lower bound of the renormalized energy when $\frac{a}{\epsilon | \ln \epsilon |}$ is bounded: Lemma 3.3 Assuming that $\frac{a}{\epsilon | \ln \epsilon |}$ is bounded, then for every $\rho_0 < \rho$:

$$\liminf_{\epsilon \to 0} \frac{1}{|\ln \epsilon|} \int_{\rho_0 \le |x| \le \rho} \frac{1}{2} |\nabla v_\epsilon|^2 \ge \frac{\pi |\mu_1|\rho}{6}, \tag{3.14}$$

where $\mu_1 = \mu'_{rad}(\rho)$.

Proof Let $\gamma \in (0, 2/3)$ and $\Omega_{\epsilon} = \{x : \rho_0 \le |x| \le \rho - \epsilon^{\gamma}\}$. The upper bound (3.13) implies that

$$\int_{\Omega_{\epsilon}} (|v_{\epsilon}|^2 - \mu)^2 = \mathcal{O}(\epsilon^2 |\ln \epsilon|).$$
(3.15)

On the other hand, we also have

$$\int_{\Omega_{\epsilon}} \frac{1}{(|v_{\epsilon}| + \sqrt{\mu})^2} \le \int_{\Omega_{\epsilon}} \frac{1}{\mu} = \mathcal{O}(|\ln \epsilon|).$$
(3.16)

Combining (3.15) with (3.16), and setting $\sigma := |v_{\epsilon}|$, we obtain

$$\int_{\Omega_{\epsilon}} |\sigma - \sqrt{\mu}| = \mathcal{O}(\epsilon |\ln \epsilon|).$$
(3.17)

At this stage, we compute a lower bound of the difference

$$\begin{split} \int_{\Omega_{\epsilon}} |\nabla \sigma|^2 &- \int_{\Omega_{\epsilon}} |\nabla \sqrt{\mu}|^2 = \int_{\Omega_{\epsilon}} |\nabla (\sigma - \sqrt{\mu})|^2 + 2 \int_{\Omega_{\epsilon}} \nabla (\sigma - \sqrt{\mu}) \nabla \sqrt{\mu} \\ &\geq 2 \int_{\Omega_{\epsilon}} (-\Delta \sqrt{\mu}) (\sigma - \sqrt{\mu}) \\ &+ \frac{\mu'_{\text{rad}}(\rho - \epsilon^{\gamma})}{\sqrt{\mu_{\text{rad}}(\rho - \epsilon^{\gamma})}} \int_{|x| = \rho - \epsilon^{\gamma}} (\sigma - \sqrt{\mu}) + \mathcal{O}(1). \end{split}$$

In view of (3.17), we have $\int_{\Omega_{\epsilon}} (-\Delta \sqrt{\mu}) (\sigma - \sqrt{\mu}) = \mathcal{O}(\epsilon^{1-\frac{3\gamma}{2}} |\ln \epsilon|)$ (since $|\Delta \sqrt{\mu}| = \mathcal{O}(\epsilon^{-\frac{3\gamma}{2}})$ on Ω_{ϵ}), while $\int_{|x|=\rho-\epsilon^{\gamma}} (\sigma - \sqrt{\mu}) = \mathcal{O}(\epsilon^{\frac{\gamma}{2}})$ by Lemma 2.3. Therefore,

$$\int_{\rho_0 \le |x| \le \rho} |\nabla v_{\epsilon}|^2 \ge \int_{\Omega_{\epsilon}} |\nabla v_{\epsilon}|^2 \ge \int_{\Omega_{\epsilon}} |\nabla \sigma|^2 \ge \int_{\Omega_{\epsilon}} |\nabla \sqrt{\mu}|^2 + \mathcal{O}(1)$$
$$= \frac{\pi |\mu_1| \rho \gamma}{2} |\ln \epsilon| + \mathcal{O}(1), \tag{3.18}$$

and $\liminf_{\epsilon \to 0} \frac{1}{|\ln \epsilon|} \int_{\rho_0 \le |x| \le \rho} \frac{1}{2} |\nabla v_{\epsilon}|^2 \ge \frac{\pi |\mu_1| \rho \gamma}{4}$. Finally, letting $\gamma \to \frac{2}{3}$ we deduce (3.14).

Now, we are going to establish

Lemma 3.4 For every $\rho_0 \in (0, \rho)$, there exists $b_* > 0$ such that when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|} < b_*$ the set of zeros of the global minimizers cannot have a limit point $l \in D(0; \rho_0)$.

The proof of Lemma 3.4 proceeds by contradiction. Let $\{\bar{x}_{\epsilon}\}$ be a sequence of zeros of $v_{\epsilon,a}$. Assuming that \bar{x}_{ϵ} converges (up to a subsequence) to a point $x_0 \in D(0; \rho_0)$, with $\rho_0 < \rho$, we will obtain the bound

$$\liminf_{\epsilon \to 0} \frac{1}{|\ln \epsilon|} \int_{D(0;\rho_0)} \left[\frac{1}{2} |\nabla v_\epsilon|^2 + \frac{(|v_\epsilon|^2 - \mu)^2}{4\epsilon^2} \right] \ge \lambda > 0, \tag{3.19}$$

which combined with (3.14), gives for $b \ll 1$ a lower bound of the renormalized energy bigger than the upper bound (3.13). The limit in (3.19) will follow from

Lemma 3.5 Let $0 < \rho_0 < \rho$, and $a(\epsilon) \le b_0 \epsilon |\ln \epsilon|$ for some $b_0 > 0$. Then, there exist constants $\lambda > 0$ and C > 0, such that for every disc $D(x_0; r_0) \subset D(0; \rho_0)$ with $r_0 \in [\epsilon, |\ln \epsilon|^{-1/2}]$, the condition

$$\int_{\partial D(x_0;r_0)} \frac{1}{2} |\nabla v_{\epsilon}|^2 + \int_{\partial D(x_0;r_0)} \frac{(|v_{\epsilon}|^2 - \mu)^2}{4\epsilon^2} \le \frac{\lambda}{r_0}$$
(3.20)

implies the bound

$$\mathcal{E}(v_{\epsilon}, D(x_0; r_0)) \le C. \tag{3.21}$$

Proof Let λ be such that

$$\sqrt{\mu_{\rm rad}(\rho_0)} - \sqrt{\frac{2\lambda}{\pi\mu_{\rm rad}(\rho_0)}} - \sqrt{4\pi\lambda} = \frac{1}{2}\sqrt{\mu_{\rm rad}(\rho_0)}.$$
 (3.22)

We first utilize inequality (3.20) to bound v_{ϵ} in modulus and argument on $\partial D(x_0; r_0)$. From

$$\int_{\partial D(x_0;r_0)} \left| |v_{\epsilon}|^2 - \mu \right|^2 \leq \frac{2\epsilon^2 \lambda}{\pi r_0^2} \leq \frac{2\lambda}{\pi},$$

it follows that there exists $\theta_0 \in \mathbb{R}$ such that $||v_{\epsilon}(x_0+r_0e^{i\theta_0})|^2 - \mu(x_0+r_0e^{i\theta_0})|^2 \leq \frac{2\lambda}{\pi}$. Thus,

$$\left| |v_{\epsilon}(x_0 + r_0 e^{i\theta_0})| - \sqrt{\mu(x_0 + r_0 e^{i\theta_0})} \right| \le \sqrt{\frac{2\lambda}{\pi \mu(x_0 + r_0 e^{i\theta_0})}} \le \sqrt{\frac{2\lambda}{\pi \mu_{\text{rad}}(\rho_0)}}.$$

On the other hand, the condition

$$\frac{1}{2r_0} \int_0^{2\pi} \left| \frac{\partial v_{\epsilon}}{\partial \theta} (x_0 + r_0 e^{i\theta}) \right|^2 \mathrm{d}\theta \le \int_{\partial D(x_0;r_0)} \frac{1}{2} |\nabla v_{\epsilon}|^2 \le \frac{\lambda}{r_0},$$

implies that $\int_0^{2\pi} \left| \frac{\partial v_{\epsilon}}{\partial \theta}(x_0 + r_0 e^{i\theta}) \right| d\theta \le \sqrt{4\pi\lambda}$, and $|v_{\epsilon}(x_0 + r_0 e^{i\theta_2}) - v_{\epsilon}(x_0 + r_0 e^{i\theta_1})| \le \sqrt{4\pi\lambda}$, for $\theta_2 \in [\theta_1, \theta_1 + 2\pi]$.

In view of (3.22), we deduce that $v_{\epsilon}(x_0 + r_0 e^{i\theta}) = \sigma(\theta)e^{i(\phi(\theta - \theta_0) + \phi_0)}$, with $\sigma(\theta) \ge \sigma_0 := \frac{1}{2}\sqrt{\mu_{\text{rad}}(\rho_0)}$, $\phi(0) = 0$, and $|\phi| \le \frac{\pi}{6}$. Indeed, we check that

$$\begin{aligned} \sigma(\theta) &\geq \sigma(\theta_0) - |\sigma(\theta_0) - \sigma(\theta)| \geq \sqrt{\mu(x_0 + r_0 e^{i\theta_0})} - \sqrt{\frac{2\lambda}{\pi \mu_{rad}(\rho_0)}} \\ &-\sqrt{4\pi\lambda} \geq \sigma_0, \ \forall \theta \in [\theta_0, \theta_0 + 2\pi], \\ |\sin(\phi(\theta - \theta_0))| &\leq \frac{\sqrt{4\pi\lambda}}{\sigma(\theta_0)} \leq \frac{\sqrt{4\pi\lambda}}{\sqrt{\mu_{rad}(\rho_0)} - \sqrt{\frac{2\lambda}{\pi \mu_{rad}(\rho_0)}}} = \frac{\sqrt{4\pi\lambda}}{\sqrt{\frac{2\lambda}{\pi \mu_{rad}(\rho_0)}} + 2\sqrt{4\pi\lambda}} \\ &\leq \frac{1}{2}, \ \forall \theta \in [\theta_0, \theta_0 + 2\pi]. \end{aligned}$$

Next, we define the comparison map

$$u(x_{0} + re^{i\theta}) = \left(\frac{r}{r_{0}}[\sigma(\theta) - \mu^{1/2}(x_{0} + r_{0}e^{i\theta})] + \mu^{1/2}(x_{0} + re^{i\theta})\right)e^{i\left(\frac{r}{r_{0}}\phi(\theta - \theta_{0}) + \phi_{0}\right)},$$

$$\forall r \in [0, r_{0}], \forall \theta \in \mathbb{R}.$$
 (3.23)

It is clear that u is continuous on $\overline{D(x_0; r_0)}$, and that $u \equiv v$ on $\partial D(x_0; r_0)$. We are going to check that $u \in H^1(D(x_0; r_0), \mathbb{R}^2)$, since actually $\int_{D(x_0; r_0)} |\nabla u|^2 \leq C$, where *C* is a positive constant depending only on μ , f, b_0 , ρ_0 and the uniform bound provided by Lemma 2.2. In what follows, it will be convenient to denote by *C* such a constant that may vary from line to line. Indeed, we have

$$\left|\frac{\partial u(x_0 + re^{i\theta})}{\partial r}\right|^2 = \left|\frac{\sigma(\theta) - \mu^{1/2}(x_0 + r_0e^{i\theta})}{r_0} + \frac{\partial \mu^{1/2}(x_0 + re^{i\theta})}{\partial r}\right|^2 + \frac{\phi^2(\theta - \theta_0)}{r_0^2} \left|\frac{r}{r_0}[\sigma(\theta) - \mu^{1/2}(x_0 + r_0e^{i\theta})] + \mu^{1/2}(x_0 + re^{i\theta})\right|^2,$$

$$\begin{aligned} \frac{1}{r^2} \Big| \frac{\partial u(x_0 + re^{i\theta})}{\partial \theta} \Big|^2 &= \Big| \frac{1}{r_0} \Big[\sigma'(\theta) - \frac{\partial \mu^{1/2}(x_0 + r_0e^{i\theta})}{\partial \theta} \Big] + \frac{1}{r} \frac{\partial \mu^{1/2}(x_0 + re^{i\theta})}{\partial \theta} \Big|^2 \\ &+ \frac{|\phi'(\theta - \theta_0)|^2}{r_0^2} \Big| \frac{r}{r_0} [\sigma(\theta) - \mu^{1/2}(x_0 + r_0e^{i\theta})] + \mu^{1/2}(x_0 + re^{i\theta}) \Big|^2. \end{aligned}$$

Hence $\int_{D(x_0;r_0)} \left| \frac{\partial u(x_0+re^{i\theta})}{\partial r} \right|^2 \leq C$. To obtain the bound $\int_{D(x_0;r_0)} \frac{1}{r^2} \left| \frac{\partial u(x_0+re^{i\theta})}{\partial \theta} \right|^2 \leq C$, we utilize (3.20) that gives $\int_0^{2\pi} |\sigma'(\theta)|^2 d\theta \leq 2\lambda$ and $\int_0^{2\pi} |\phi'(\theta-\theta_0)|^2 d\theta \leq \frac{2\lambda}{\sigma_0^2}$. Finally, from (3.23) we can see that

and since $\int_0^{2\pi} \frac{(|v_{\epsilon}(x_0+r_0e^{i\theta})|^2-\mu(x_0+re^{i\theta}))^2}{4\epsilon^2} \leq \frac{\lambda}{r_0^2}$ by (3.20), we deduce that $\int_{D(x_0;r_0)} \frac{(|u|^2-\mu)^2}{4\epsilon^2} \leq C$. On the other hand, it is obvious that $-\frac{a}{\epsilon} \int_{D(x_0;r_0)} f \cdot u \leq C$; thus, we obtain by minimality of v_{ϵ} :

$$\mathcal{E}(v_{\epsilon}, D(x_0; r_0)) \le \mathcal{E}(u, D(x_0; r_0)) \le C,$$

which completes the proof.

Proof of Lemma 3.4 We assume that $\sup \frac{a}{\epsilon |\ln \epsilon|} \le b_0$, where b_0 is an arbitrary constant. Suppose by contradiction that \bar{x}_{ϵ} converges (up to a subsequence) to a point $x_0 \in D(0; \rho_0)$ (with $\rho_0 < \rho$), and consider the rescaled maps $\tilde{v}_{\epsilon}(s) = v_{\epsilon}(\bar{x}_{\epsilon} + \epsilon s)$ satisfying

$$\Delta \tilde{v}(s) + \mu(\bar{x}_{\epsilon} + \epsilon s)\tilde{v}(s) - |\tilde{v}(s)|^2\tilde{v}(s) + \epsilon af(\bar{x}_{\epsilon} + \epsilon s) = 0, \ \forall s \in \mathbb{R}^2.$$
(3.24)

In view of the Lemma 2.2 and (3.24), the first derivatives of \tilde{v}_{ϵ} are uniformly bounded for $\epsilon \ll 1$. Moreover, by differentiating (3.24), one also obtains the boundedness of the second derivatives of \tilde{v} on compact sets. Thus, we can apply the theorem of Ascoli via a diagonal argument and show that for a subsequence still called \tilde{v}_{ϵ} , \tilde{v}_{ϵ} converges in $C_{\rm loc}^2(\mathbb{R}^2, \mathbb{R}^2)$ to a map \tilde{V} , that we are now going to determine. For this purpose, we introduce the rescaled energy

$$\begin{split} \tilde{E}(\tilde{u}) &= \int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \tilde{u}(s)|^2 - \frac{1}{2} \mu (\bar{x}_{\epsilon} + s\epsilon) |\tilde{u}(s)|^2 + \frac{1}{4} |\tilde{u}(s)|^4 - \epsilon a f(\bar{x}_{\epsilon} + s\epsilon) \cdot \tilde{u}(s) \right) \mathrm{d}s \\ &= E(u), \end{split}$$

where we have set $\tilde{u}(s) = u_{\epsilon}(\bar{x}_{\epsilon} + s\epsilon)$, i.e. $u_{\epsilon}(x) = \tilde{u}\left(\frac{x-\bar{x}_{\epsilon}}{\epsilon}\right)$. Let $\tilde{\xi}$ be a test function with support in the compact set K. We have $\tilde{E}(\tilde{v}_{\epsilon} + \tilde{\xi}, K) \geq \tilde{E}(\tilde{v}_{\epsilon}, K)$, and at the

limit $G_0(\tilde{V} + \tilde{\xi}, K) \ge G_0(\tilde{V}, K)$, where

$$G_0(\psi, K) = \int_K \left[\frac{1}{2} |\nabla \psi|^2 - \frac{1}{2} \mu(x_0) |\psi|^2 + \frac{1}{4} |\psi|^4 \right],$$

or equivalently $G(\tilde{V} + \tilde{\xi}, K) \ge G(\tilde{V}, K)$, where

$$G(\psi, K) = \int_{K} \left[\frac{1}{2} |\nabla \psi|^{2} - \frac{1}{2} \mu(x_{0}) |\psi|^{2} + \frac{1}{4} |\psi|^{4} + \frac{(\mu(x_{0}))^{2}}{4} \right]$$
$$= \int_{K} \left[\frac{1}{2} |\nabla \psi|^{2} + \frac{1}{4} (|\psi|^{2} - \mu(x_{0}))^{2} \right].$$
(3.25)

Thus, we deduce that \tilde{V} is a bounded minimal solution of the P.D.E. associated with the functional (3.25):

$$\Delta \tilde{V}(s) + (\mu(x_0) - |\tilde{V}(s)|^2)\tilde{V}(s) = 0, \qquad (3.26)$$

and since $\tilde{V}(0) = 0$, we obtain (up to orthogonal transformation in the range) $\tilde{V}(s) = \sqrt{\mu(x_0)} \eta(\sqrt{\mu(x_0)}s)$, where $\eta(s) = \eta_{rad}(|s|)\frac{s}{|s|}$ is the radial solution to the Ginzburg–Landau equation (1.9). It is known that $\int_{\mathbb{R}^2} |\nabla \eta|^2 = \infty$. Therefore, if q > 1 is such that

$$3C < \mu_{\rm rad}(\rho_0) \int_{D(0;q\sqrt{\mu_{\rm rad}(\rho_0)})} |\nabla\eta|^2 \le \mu(x_0) \int_{D(0;q\sqrt{\mu(x_0)})} |\nabla\eta|^2 = \int_{D(0;q)} |\nabla\tilde{V}|^2,$$

where *C* is the constant given in Lemma 3.5, then for $\epsilon \leq \epsilon_0$ small enough, we have $\frac{3C}{2} < \frac{1}{2} \int_{D(\bar{x}_{\epsilon};q\epsilon)} |\nabla v_{\epsilon}|^2$. In addition, by taking $\delta > 0$ sufficiently small, we can ensure that $\mathcal{E}(v_{\epsilon}, D(\bar{x}_{\epsilon};r)) > C$, for every $r \in [q\epsilon, \delta|\ln\epsilon|^{-1/2}]$, and every $\epsilon \leq \epsilon_0$. Next, applying Lemma 3.5, we obtain for $r \in [q\epsilon, \delta|\ln\epsilon|^{-1/2}]$ and $\epsilon \leq \epsilon_0$ the inequality:

$$\int_{\partial D(\bar{x}_{\epsilon};r)} \frac{1}{2} |\nabla v_{\epsilon}|^2 + \int_{\partial D(\bar{x}_{\epsilon};r)} \frac{(|v_{\epsilon}|^2 - \mu)^2}{4\epsilon^2} > \frac{\lambda}{r}.$$
(3.27)

Finally, an integration of (3.27) gives

$$\begin{split} \int_{D(\bar{x}_{\epsilon};\delta)} \frac{1}{2} |\nabla v_{\epsilon}|^2 + \int_{D(\bar{x}_{\epsilon};\delta)} \frac{(|v_{\epsilon}|^2 - \mu)^2}{4\epsilon^2} \geq \int_{q\epsilon}^{\delta |\ln\epsilon|^{-1/2}} \frac{\lambda}{r} \mathrm{d}r \geq \lambda |\ln\epsilon| \\ - \frac{\lambda}{2} \ln(|\ln\epsilon|) + \mathcal{O}(1), \end{split}$$

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from which (3.19) follows. Combining (3.14) with (3.19), we obtain

$$\begin{split} \liminf_{\epsilon \to 0} \frac{1}{|\ln \epsilon|} \mathcal{E}(v_{\epsilon}) &\geq \frac{\pi |\mu_1|\rho}{6} + \lambda + \liminf_{\epsilon \to 0} \left(-\frac{a}{\epsilon |\ln \epsilon|} \int_{\mathbb{R}^2} f \cdot v_{\epsilon} \right) \\ &\geq \frac{\pi |\mu_1|\rho}{6} + \lambda - M \|f\|_{L^1} \limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|}, \end{split}$$

with $M \ge \|v_{\epsilon}\|_{L^{\infty}}$ (cf. Lemma 2.2). Then, we can see that the upper bound (3.13) is violated when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|} < b_* := \min\left(\frac{\lambda}{M\|f\|_{L^1}}, b_0\right)$. Therefore, the convergence of \bar{x}_{ϵ} to a point x_0 such that $|x_0| < \rho_0$ is excluded provided $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|} < b_*$.

To complete the proof, we utilize part (i) of Theorem 1.2 and deduce that any limit point $l \in \mathbb{R}^2$ of the set of zeros of the global minimizers satisfies (1.11). When $a = o(\epsilon | \ln \epsilon |)$, it is immediate that $|l| = \rho$.

Theorem 1.2 (iii) In the set $\Omega_v := \{x \in \mathbb{R}^2 : v(x) \neq 0\}$, we consider the polar form of v:

$$v(x) = |v(x)| \frac{v(x)}{|v(x)|} =: \sigma(x) \mathbf{n}(x), \text{ where } \sigma(x) := |v(x)|, \ \mathbf{n}(x) := \frac{v(x)}{|v(x)|}.$$
(3.28)

Setting

$$F(x) = \begin{cases} 0 & \text{when } v(x) = 0, \\ |\nabla \sigma(x)|^2 + \sigma^2(x) |\nabla n(x)|^2, & \text{when } v(x) \neq 0, \end{cases}$$
(3.29)

we get (cf. [13])

$$\int_{\mathbb{R}^2} |\nabla v(x)|^2 \mathrm{d}x = \int_{\mathbb{R}^2} F(x) \mathrm{d}x = \int_{\Omega_v} \left(|\nabla \sigma(x)|^2 + \sigma^2(x) |\nabla \boldsymbol{n}(x)|^2 \right) \mathrm{d}x. \quad (3.30)$$

The next Lemma which is based on the previous decomposition provides some information on the direction of the vector field v:

Lemma 3.6 Assuming that a is bounded and $\rho_1 > \rho$, there exists a constant K, such that

$$\int_{\Omega_{v} \cap \{|x| \le \rho_{1}\}} \left(\frac{1}{2}\sigma^{2} |\nabla \mathbf{n}|^{2} + \frac{a}{\epsilon} |f| \sigma \left[1 - \frac{x}{|x|} \cdot \mathbf{n}\right]\right) \le K |\ln \epsilon| \text{ for } \epsilon \ll 1.$$
(3.31)

Proof We define the constants:

- M > 0 which is the uniform bound of $|v_{\epsilon,a}|$,
- $\rho_2 = \rho_1 + 1$.

Next writing $x = re^{i\theta}$, we consider the comparison map

$$\psi(re^{i\theta}) = \begin{cases} \frac{r}{\epsilon}\sigma(\epsilon e^{i\theta})e^{i\theta} & \text{for } r \in [0,\epsilon], \\ \sigma(x)e^{i\theta} & \text{for } r \in [\epsilon,\rho_1], \\ \frac{r-\rho_1}{\rho_2-\rho_1}v(x) + \frac{\rho_2-r}{\rho_2-\rho_1}\sigma(x)e^{i\theta} & \text{for } r \in [\rho_1,\rho_2]. \end{cases}$$

It is clear that $\psi \in H^1(D(0; \rho_2), \mathbb{R}^2)$ and that $\psi \equiv v$ for $|x| = \rho_2$, thus

$$\mathcal{E}(v, D(0; \rho_2)) - \mathcal{E}(\psi, D(0; \rho_2)) \le 0.$$
(3.32)

Since $\epsilon \nabla v$ is uniformly bounded on \mathbb{R}^2 (cf. Lemma 2.2), and $\frac{v}{\epsilon}$ as well as ∇v are uniformly bounded on $\{|x| \ge \rho_1\}$ (cf. Lemma 2.4), one can check that

$$\begin{split} \mathcal{E}(v, D(0; \epsilon)) - \mathcal{E}(\psi, D(0; \epsilon)) &\leq K, \\ \mathcal{E}(v, \{\rho_1 \leq |x| \leq \rho_2\}) - \mathcal{E}(\psi, \{\rho_1 \leq |x| \leq \rho_2\})) &\leq K, \end{split}$$

where *K* is a constant depending only on μ , *f*, ρ_1 and the previous uniform bounds, that may vary from line to line. Therefore,

$$\int_{\Omega_{\nu} \cap \{\epsilon \le |x| \le \rho_1\}} \left(\frac{1}{2} (|\nabla \nu|^2 - |\nabla \psi|^2) + \frac{a}{\epsilon} (|f|\sigma - f \cdot \nu) \right) \le K, \qquad (3.33)$$

and since $(|\nabla v(x)|^2 - |\nabla \psi(x)|^2) = \sigma^2(x)|\nabla n(x)|^2 - \frac{\sigma^2(x)}{|x|^2}$ holds for $x \in \Omega_v \cap \{\epsilon \le |x| \le \rho_1\}$, we deduce that

$$\int_{\Omega_{v} \cap \{\epsilon \leq |x| \leq \rho_{1}\}} \left(\frac{1}{2}\sigma^{2} |\nabla \boldsymbol{n}|^{2} + \frac{a}{\epsilon}(|f|\sigma - f \cdot v)\right)$$

$$\leq \pi M^{2}(|\ln \epsilon| + \ln \rho_{1}) + K \text{ for } \epsilon \ll 1.$$
(3.34)

Finally, (3.31) follows by combining (3.34) with

$$\int_{\Omega_{v} \cap \{|x| \le \epsilon\}} \left(\frac{1}{2} \sigma^{2} |\nabla \boldsymbol{n}|^{2} + \frac{a}{\epsilon} (|f|\sigma - f \cdot v) \right) \le K,$$
(3.35)

and adjusting the constant K.

Now, we prove

Lemma 3.7 For every $\rho_0 \in (0, \rho)$, there exists $b^* > 0$ such that when a is bounded and $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} > b^*$, the zeros of the global minimizers have a limit point l such that $|l| \le \rho_0$. In particular, the condition $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} = \infty$ with a bounded, implies the existence of a zero $\bar{x}_{\epsilon} \to 0$.

Proof Assume by contradiction that the zeros of the global minimizers v_{ϵ} have no limit point such that $|l| \leq \rho_0$. As a consequence, there exists $\epsilon_0 > 0$ such that $\forall \epsilon < \epsilon_0$, $\forall x \in \overline{D(0; \rho_0)}$: $v_{\epsilon}(x) \neq 0$. Moreover, proceeding as in the proof of Theorem 1.1 (i), we can see that $|v_{\epsilon}|$ converges uniformly on $\overline{D(0; \rho_0)}$ to $\sqrt{\mu}$, as $\epsilon \to 0$. Thus, for $\epsilon \ll 1$, we have

$$\underline{\min}_{\overline{D(0;\rho_0)}} \sigma_{\epsilon}^2 \ge \frac{1}{2} \mu_{\mathrm{rad}}(\rho_0),$$

and from (3.31) we deduce that

$$\int_{|x| \le \rho_0} |\nabla \boldsymbol{n}|^2 \le K_1 |\ln \epsilon|, \quad \frac{a}{\epsilon} \int_{\rho_0/2 \le |x| \le \rho_0} \left[1 - \frac{x}{|x|} \cdot \boldsymbol{n} \right] \le K_2 |\ln \epsilon| \text{ for } \epsilon \ll 1,$$
(3.36)

where K_i (i = 1, 2) are constants. At this stage, we notice that since for every $\epsilon < \epsilon_0$, v_ϵ does not vanish on $\overline{D(0; \rho_0)}$, the degree of v_ϵ on the circles |x| = r, with $r \in (0, \rho_0]$, is zero. In particular, we can write $\mathbf{n}(re^{i\theta}) = e^{i\phi_r(\theta)}$, where $\phi_r : \mathbb{R} \to \mathbb{R}$ is a 2π periodic smooth function, for every $r \in (0, \rho_0]$. Now, we define the measurable sets

- $F := \left\{ x : \frac{\rho_0}{2} \le |x| \le \rho_0, \frac{x}{|x|} \cdot \boldsymbol{n} \le \frac{1}{2} \right\} = \left\{ x = r e^{i\theta} : \frac{\rho_0}{2} \le r \le \rho_0, \ \phi_r(\theta) \theta \notin (-\pi/3, \pi/3) \mod 2\pi \right\},$
- $F_r := \{ \theta \in [0, 2\pi] : \phi_r(\theta) \theta \notin (-\pi/3, \pi/3) \mod 2\pi \},$

•
$$R := \left\{ r \in [\rho_0/2, \rho_0] : \mathcal{L}^1(F_r) < \frac{16\epsilon}{a\rho_0^2} K_2 |\ln \epsilon| \right\},$$

• $R^c := \left\{ r \in [\rho_0/2, \rho_0] : \mathcal{L}^1(F_r) \ge \frac{16\epsilon}{a\rho_0^2} K_2 |\ln \epsilon| \right\} = [\rho_0/2, \rho_0] \setminus R,$

where \mathcal{L}^n denotes the *n*-dimensional Lebesgue measure. It follows from these definitions and (3.36) that

$$\frac{4}{\rho_0} K_2 |\ln \epsilon| \mathcal{L}^1(R^c) \le \frac{a\rho_0}{4\epsilon} \int_{\rho_0/2}^{\rho_0} \mathcal{L}^1(F_r) \mathrm{d}r \le \frac{a}{2\epsilon} \mathcal{L}^2(F) \le K_2 |\ln \epsilon|, \text{ for } \epsilon \ll 1,$$
(3.37)

thus $\mathcal{L}^1(R) \geq \frac{\rho_0}{4}$. Moreover, since ϕ_r is periodic, for every $r \in [\rho_0/2, \rho_0]$ there exist $\theta_1(r) \in \mathbb{R}$ and $\theta_2(r) \in (\theta_1(r), \theta_1(r) + 2\pi)$, such that $\phi_r(\theta_1(r)) - \theta_1(r) = \frac{5\pi}{3}$, $\phi_r(\theta_2(r)) - \theta_2(r) = \frac{\pi}{3}$, and $\phi_r(\theta) - \theta \in (\frac{\pi}{3}, \frac{5\pi}{3})$ for $\theta \in (\theta_1(r), \theta_2(r))$. By definition of F_r , we also have $\theta_2(r) - \theta_1(r) \leq \mathcal{L}^1(F_r)$. Next, using the Cauchy–Schwarz inequality we obtain

$$\frac{(4\pi)^2}{3^2} = \left(\int_{\theta_1(r)}^{\theta_2(r)} (\phi_r'(\theta) - 1) \mathrm{d}\theta\right)^2 \le (\theta_2(r) - \theta_1(r)) \int_{\theta_1(r)}^{\theta_2(r)} |\phi_r'(\theta) - 1|^2 \mathrm{d}\theta.$$

As a consequence,

$$\frac{(4\pi)^2}{3^2 \mathcal{L}^1(F_r)} \leq \frac{(4\pi)^2}{3^2 (\theta_2(r) - \theta_1(r))} \leq \int_{\theta_1(r)}^{\theta_2(r)} |\phi_r'(\theta) - 1|^2 \mathrm{d}\theta \Rightarrow \frac{(4\pi)^2}{3^2 \mathcal{L}^1(F_r)} - \frac{8\pi}{3} \leq \int_{\theta_1(r)}^{\theta_2(r)} |\phi_r'(\theta)|^2 \mathrm{d}\theta,$$

and

$$K_{1}|\ln\epsilon| \geq \int_{\rho_{0}/2 \leq |x| \leq \rho_{0}} |\nabla \boldsymbol{n}|^{2} \geq \int_{\rho_{0}/2}^{\rho_{0}} \frac{\mathrm{d}r}{r} \int_{0}^{2\pi} |\boldsymbol{n}_{\theta}(r,\theta)|^{2} \mathrm{d}\theta$$

$$= \int_{\rho_{0}/2}^{\rho_{0}} \frac{\mathrm{d}r}{r} \int_{0}^{2\pi} |\phi_{r}'(\theta)|^{2} \mathrm{d}\theta$$

$$\geq \frac{1}{\rho_{0}} \int_{R} \frac{(4\pi)^{2} \mathrm{d}r}{3^{2} \mathcal{L}^{1}(F_{r})} - \frac{4\pi}{3} \geq \frac{(\pi\rho_{0})^{2}a}{6^{2} K_{2}\epsilon|\ln\epsilon|} - \frac{4\pi}{3}.$$
(3.38)

Now, we can see that (3.38) is violated when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} > \frac{6^2 K_1 K_2}{(\pi \rho_0)^2} =: b^*$. Therefore, we have proved the existence of a limit point $l \in \overline{D(0; \rho_0)}$ provided $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} > b^*$ (with *a* bounded). The previous argument also establishes the existence of a sequence $\bar{x}_{\epsilon} \to 0$ when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} = \infty$ with *a* bounded. \Box

Finally, if $v_{\epsilon,a}(\bar{x}_{\epsilon}) = 0$ and $\bar{x}_{\epsilon} \to l$, we consider the rescaled maps $\tilde{v}_{\epsilon}(s) = v_{\epsilon}(\bar{x}_{\epsilon} + \epsilon s)$ and proceeding as in the proof of Theorem 1.1 (i) we obtain up to subsequence

$$\lim_{\epsilon \to 0} v_{\epsilon,a}(\bar{x}_{\epsilon} + \epsilon s) \to \sqrt{\mu(l)}(g \circ \eta)(\sqrt{\mu(l)}s),$$

in $C^2_{\text{loc}}(\mathbb{R}^2)$, for some $g \in O(2)$.

Proof of Theorem 1.3 (*i*) We first notice that $v \neq 0$ for $\epsilon \ll 1$. Indeed, by choosing a test function of the form $\psi = (\sqrt{\mu_{\text{rad}}}, 0)\chi(\frac{\rho-r}{\epsilon^{2/3}})$, with χ a cut-off function supported in the left half line, one can see that

$$E(\psi) \leq -\frac{1}{4\epsilon^2} \int_0^\rho \mu_{\rm rad}^2(r) r dr + O(|\ln \epsilon|) < 0, \qquad \epsilon \ll 1.$$

Let $x_0 \in \mathbb{R}^2$ be such that $v(x_0) \neq 0$. Without loss of generality, we may assume that $v(x_0) = (v_1(x_0), 0)$ is contained in the open right half-plane $P = \{x_1 > 0\}$. Next, consider $\tilde{v} = (|v_1|, v_2)$ which is another global minimizer and thus another solution. Clearly, in a sufficiently small disc $D \subset P$ centred at $v(x_0)$ we have $v_1 = |v_1| > 0$, and as a consequence of the unique continuation principle (cf. [22]), we deduce that $v \equiv \tilde{v}$ on $\mathbb{R}^2 \Rightarrow v(\mathbb{R}^2) \subset \overline{P}$. Since the same conclusion holds for any open half-plane containing $v(x_0)$, we also obtain $v(\mathbb{R}^2) \subset \{\lambda v(x_0) : \lambda \geq 0\}$. As a consequence, we have $v = (v_1, 0)$ with $v_1 \geq 0$, and $\epsilon^2 \Delta v_1 + \mu v_1 - v_1^3 = 0$. By the maximum principle, it follows that $v_1 > 0$ since $v_1 \not\equiv 0$.

Now to prove that v_1 is radial consider the reflection with respect to the line $x_1 = 0$. We can check that $E(v, \{x_1 > 0\}) = E(v, \{x_1 < 0\})$, since otherwise by even reflection we can construct a map in H^1 with energy smaller than v. Thus, the map $\tilde{v}(x) = v(|x_1|, x_2)$ is also a minimizer, and since $\tilde{v} = v$ on $\{x_1 > 0\}$, it follows by unique continuation that $\tilde{v} \equiv v$ on \mathbb{R}^2 . Repeating the same argument for any line of reflection, we deduce that v_1 is radial. To complete the proof, it remains to show the uniqueness of v up to rotations. Let $\tilde{v} = (\tilde{v}_1, 0)$ be another global minimizer with $\tilde{v}_1 > 0$ and $\tilde{v}_1 \neq v_1$. Putting $\psi = v$ in (1.4):

$$\int_{\mathbb{R}^2} -\epsilon^2 |\nabla v|^2 + \mu |v|^2 - |v|^4 = 0 \Rightarrow E(v) = -\int_{\mathbb{R}^2} \frac{1}{4\epsilon^2} |v|^4, \qquad (3.39)$$

we obtain an alternative expression of the energy that holds for every solution of (1.3) belonging to H^1 . In particular, this formula implies that v_1 and \tilde{v}_1 intersect for |x| = r > 0. However, setting

$$w(x) = \begin{cases} v(x) & \text{for } |x| \le r\\ \tilde{v}(x) & \text{for } |x| \ge r, \end{cases}$$

we can see that w is another global minimizer, and again by the unique continuation principle, we have $w \equiv v \equiv \tilde{v}$.

Proof of Theorem 1.3 (*ii*) We need first to establish the three Lemmas below. \Box

Lemma 3.8 If u is a solution of (1.3) belonging to $H^1(\mathbb{R}^2, \mathbb{R}^2)$, then for every $\psi \in H^1(\mathbb{R}^2, \mathbb{R}^2)$, we have

$$E(u+\psi) - E(u) = \int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \psi|^2 + \frac{(|u|^2 - \mu)}{2\epsilon^2} |\psi|^2 + \frac{(|\psi|^2 + 2(u \cdot \psi))^2}{4\epsilon^2} \right).$$
(3.40)

Proof The Euler–Lagrange equation (1.4) gives

$$\int_{\mathbb{R}^2} \left(\sum_{j=1,2} \nabla \psi_j \cdot \nabla u_j \right) = \int_{\mathbb{R}^2} \left(\frac{\mu}{\epsilon^2} \psi \cdot u - \frac{|u|^2 \psi \cdot u}{\epsilon^2} + \frac{a}{\epsilon} f \cdot \psi \right).$$
(3.41)

On the other hand, we have the identity

$$\int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \psi + \nabla u|^2 + \frac{1}{2} |\nabla u|^2 - \sum_{j=1,2} (\nabla \psi_j + \nabla u_j) \cdot \nabla u_j \right) = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla \psi|^2.$$
(3.42)

Adding (3.41) and (3.42), we obtain

$$\int_{\mathbb{R}^2} \frac{1}{2} \left(|\nabla(\psi+u)|^2 - |\nabla u|^2 \right)$$
$$= \int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \psi|^2 + \frac{\mu}{\epsilon^2} \psi \cdot u - \frac{|u|^2 \psi \cdot u}{\epsilon^2} + \frac{a}{\epsilon} f \cdot \psi \right) =: B, \qquad (3.43)$$

and thus

$$\begin{split} E(u+\psi) - E(u) &= B + \int_{\mathbb{R}^2} \left(-\frac{\mu}{2\epsilon^2} (|u+\psi|^2 - |u|^2) \right. \\ &+ \frac{1}{4\epsilon^2} (|u+\psi|^4 - |u|^4) - \frac{a}{\epsilon} f \cdot \psi \right) \\ &= \int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \psi|^2 + \frac{(|u|^2 - \mu)}{2\epsilon^2} |\psi|^2 + \frac{(|\psi|^2 + 2(u \cdot \psi))^2}{4\epsilon^2} \right). \end{split}$$

Lemma 3.9 For every a > 0, let $\mu_a : \mathbb{R}^2 \to \mathbb{R}$ be a measurable function satisfying $\mu_a \leq \mu$, and $\lim_{a\to\infty} \mu_a = -\infty$ a.e., then given $\epsilon > 0$ there exists A > 0 such that for every a > A we have

$$\int_{\mathbb{R}^2} \mu_a |\psi|^2 < \epsilon^2 \int_{\mathbb{R}^2} |\nabla \psi|^2, \quad \forall \psi \in H^1(\mathbb{R}^2, \mathbb{R}^2), \ \psi \neq 0.$$
(3.44)

Proof By homogeneity, it is sufficient to prove (3.44) for $\|\psi\|_{H^1} = 1$. Suppose by contradiction that (3.44) does not hold. Then, there exist a constant $C_0 > 0$, a sequence $a_n \to \infty$, and a sequence $\psi_n \in H^1(\mathbb{R}^2, \mathbb{R}^2)$, with $\|\psi_n\|_{H^1} = 1$, such that

$$\int_{\mathbb{R}^2} \mu_{a_n} |\psi_n|^2 \ge C_0 \int_{\mathbb{R}^2} |\nabla \psi_n|^2.$$
(3.45)

Since $\|\psi_n\|_{H^1}$ is bounded, we can extract a subsequence, still called ψ_n , such that $\psi_n \rightharpoonup \Psi$ weakly in H^1 , and $\psi_n \rightarrow \Psi$ in L^2_{loc} . Writing

$$C_0 \int_{\mathbb{R}^2} |\nabla \psi_n|^2 \le \int_{\mathbb{R}^2} \mu_{a_n} |\psi_n|^2 \le \int_{I_{\delta}} \max(\mu_{a_n}, 0) |\psi_n|^2,$$

where $I_{\delta} := \{x \in \mathbb{R}^2 : \mu(x) > -\delta\}$ and $\delta > 0$ is small, we see that $\lim_{n\to\infty} \int_{\mathbb{R}^2} |\nabla \psi_n|^2 = 0$. This implies by lower semicontinuity that $\int_{\mathbb{R}^2} |\nabla \Psi|^2 \leq \lim_{n\to\infty} \int_{\mathbb{R}^2} |\nabla \psi_n|^2 = 0$, hence $\Psi \equiv 0$. In addition, we have $\lim_{n\to\infty} \int_{\mathbb{R}^2} |\psi_n|^2 = 1$, $\lim_{n\to\infty} \int_{I_{\delta}} |\psi_n|^2 = 0$, and $\lim_{n\to\infty} \int_{\mathbb{R}^2 \setminus I_{\delta}} |\psi_n|^2 = 1$. As a consequence,

$$\int_{\mathbb{R}^2} \mu_{a_n} |\psi_n|^2 \le \|\mu\|_{L^{\infty}} \int_{I_{\delta}} |\psi_n|^2 - \delta \int_{\mathbb{R}^2 \setminus I_{\delta}} |\psi_n|^2,$$

and taking the limit we find that $\int_{\mathbb{R}^2} \mu_{a_n} |\psi_n|^2 \le -\frac{\delta}{2}$, for *n* big enough, which contradicts (3.45).

Lemma 3.10 For $\epsilon > 0$ and $x_0 \in \mathbb{R}^2$ fixed, the global minimizers satisfy

$$\lim_{a \to \infty} a^{-1/3} v_{\epsilon,a}(x_0 + a^{-1/3}s) = \frac{\epsilon^{1/3} f(x_0)}{|f(x_0)|^{2/3}},$$
(3.46)

for the $C^2_{\text{loc}}(\mathbb{R}^2, \mathbb{R}^2)$ convergence.

Proof We consider the rescaled maps $\tilde{v}(s) = a^{-1/3}v(x_0 + a^{-1/3}s)$, satisfying

$$\epsilon^{2} \Delta \tilde{v}(s) + a^{-2/3} \mu(x_{0} + a^{-1/3}s) \tilde{v}(s) - |\tilde{v}|^{2}(s) \tilde{v}(s) + \epsilon f(x_{0} + a^{-1/3}s) = 0, \ \forall s \in \mathbb{R}^{2}.$$
(3.47)

Repeating the arguments in the proof of Lemma 2.2, one can see that when ϵ is fixed and $\frac{1}{a}$ remains bounded, the maps $\tilde{v}_{\epsilon,a}$ are uniformly bounded up to the second derivatives. Therefore, proceeding as in the proof of Theorem 1.1 (i) and (ii), we deduce the convergence of \tilde{v} as $a \to \infty$ to the unique bounded solution of

$$\epsilon^2 \Delta \tilde{V}(s) - |\tilde{V}(s)|^2 \tilde{V}(s) + \epsilon f(x_0) = 0, \ \forall s \in \mathbb{R}^2,$$
(3.48)

which is the constant $\tilde{V} \equiv \frac{\epsilon^{1/3} f(x_0)}{|f(x_0)|^{2/3}}$.

Let $\epsilon > 0$ be fixed and let $\mu_a := \mu - |v|^2$, where $v := v_{\epsilon,\alpha}$ is a global minimizer. By Lemma 3.10, we know that for every $x \neq 0$, $\mu_a(x)$ converges pointwise to $-\infty$, as $a \to \infty$. Thus, by (3.44), there exists A > 0, such that for every a > A we have

$$\int_{\mathbb{R}^2} \left(\frac{1}{2} |\nabla \psi|^2 + \frac{(|v|^2 - \mu)}{2\epsilon^2} |\psi|^2 \right) > 0, \quad \forall \psi \in H^1(\mathbb{R}^2, \mathbb{R}^2), \quad \psi \neq 0$$

and also $E(v + \psi) > E(v)$ in view of (3.40). In particular, it follows that when a > A, the global minimizer is unique and radial, since $v \equiv g^{-1}vg$, $\forall g \in O(2)$.

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