

P2) Primer caso: $h_i \leq h \leq H_0$ $0 \leq t \leq \tilde{t}$

$$\frac{dV}{dt} = Q_e - Q_s \quad \begin{matrix} \nearrow \\ Q_a \end{matrix}$$

$$V = h \cdot A$$

$$\frac{dV}{dt} = A \frac{dh}{dt}$$

$$A \frac{dh}{dt} = Q_a$$

$$\int_{h_i}^h A dh = \int_0^t Q_a dt$$

$$A h \Big|_{h_i}^h = Q_a t \Big|_0^t$$

$$A(h - h_i) = Q_a t$$

$$h(t) = \frac{Q_a t}{A} + h_i$$

$$\boxed{h(t) = 4 + 0,00002 t} \quad t \text{ en seg.}$$

$\tilde{t}$: tiempo en que $h = H_0$: $H_0 = 4 + 0,00002 \tilde{t}$

$\tilde{t} = 50000 \text{ seg.} = 9,579 \text{ días}$

Segundo caso: $h > H_0$ $\tilde{t} \leq t \leq T^*$

$$\frac{dV}{dt} = A \frac{dh}{dt} = Q_e - Q_s$$

$\begin{matrix} \nearrow & \nearrow \\ Q_a & \alpha z \\ & = \alpha(h - H_0) \end{matrix}$

$$A \frac{dh}{dt} = Q_a - \alpha h + \alpha H_0$$

$$\int_{H_0}^h \frac{A dh}{Q_a + \alpha H_0 - \alpha h} = \int_{\tilde{t}}^t dt$$

$$-\frac{A}{\alpha} \ln(Q_a + \alpha H_0 - \alpha h) \Big|_{H_0}^h = t \Big|_{\tilde{t}}^t$$

$$\ln\left(\frac{Q_a + \alpha H_0 - \alpha h}{Q_a}\right) = -\frac{\alpha}{A}(t - \tilde{t})$$

$$-\alpha h = Q_a e^{\frac{\alpha}{A}(\tilde{t} - t)} - Q_a - \alpha H_0$$

$$\boxed{h = H_0 + \frac{Q_a}{\alpha} \left[1 - e^{\frac{\alpha}{A}(\tilde{t} - t)} \right]}$$

función creciente con t , Tiende a $h(t \rightarrow \infty) = H_0 + \frac{Q_a}{\alpha} = 5,5$

En $t = T^* = 2,5 \text{ días} = 216000 \text{ seg.}$

$$\boxed{h = 5,499 \text{ m}}$$

Tercer caso: $h > H_0$ $t > T^*$

$$\frac{d\dot{V}}{dt} = \overset{0}{Q_e} - Q_s \quad \nwarrow \alpha(h-H_0)$$

$$A \frac{dh}{dt} = -\alpha(h-H_0)$$

$$\int_{h(T^*)}^h \frac{A dh}{\alpha(H_0-h)} = \int_{T^*}^t dt$$

$$-\frac{A}{\alpha} \ln(H_0-h) \Big|_{h(T^*)}^h = t - T^*$$

$$\frac{A}{\alpha} \ln \left[\frac{H_0-h}{H_0-h(T^*)} \right] = T^* - t$$

$$H_0 - h = (H_0 - h(T^*)) \cdot e^{\frac{\alpha}{A}(T^*-t)}$$

$$\boxed{h = H_0 + (h(T^*) - H_0) e^{\frac{\alpha}{A}(T^*-t)}}$$

función decreciente con t

$$h(t \rightarrow \infty) = H_0$$

