



a) Caudal: $B_0 = B_2 \Rightarrow H_0 = H_d + \frac{v^2}{2g}$

$$\Rightarrow v^2 = 2g(H_0 - H_d) \Rightarrow v = \sqrt{2g(H_0 - H_d)}$$

$$\therefore Q = v \cdot A = \sqrt{2g(H_0 - H_d)} \cdot \frac{\pi d^2}{4}$$

b) Ec. diferencial.

si $h > H_d$

$$\frac{L}{g} \frac{dv}{dt} + B_2 - B_1 = 0$$

$$B_1 = B_0 = H_0$$

$$B_2 = B_3 = h + \frac{v^2}{2g} \quad \text{con } v \text{ veloc. del estancque.}$$

$$\Rightarrow \frac{L}{g} \frac{dv}{dt} + h + \frac{v^2}{2g} - H_0 = 0$$

$$Q = v \frac{\pi D^2}{4} = \frac{dh}{dt} \frac{\pi D^2}{4} = u \frac{\pi d^2}{4} \Rightarrow \frac{\pi D^2}{4} \frac{d^2 h}{dt^2} = \frac{\pi d^2}{4} \frac{dv}{dt}$$

$$\Rightarrow \frac{L}{g} \left(\frac{D}{d}\right)^2 \frac{d^2 h}{dt^2} + h + \left(\frac{dh}{dt}\right)^2 \frac{1}{2g} - H_0 = 0$$

$$\frac{L}{g} \frac{d^2 h}{dt^2} + \left(\frac{d}{D}\right)^2 h + \left(\frac{dh}{dt}\right)^2 \frac{1}{2g} \left(\frac{d}{D}\right)^2 - H_0 \left(\frac{d}{D}\right)^2 = 0$$

$$\frac{d^2 h}{dt^2} + \left(\frac{d}{D}\right)^2 \frac{g}{L} h - H_0 \left(\frac{d}{D}\right)^2 \frac{g}{L} = 0$$

$$\frac{d^2 h}{dt^2} + \left(\frac{d}{D}\right)^2 \frac{g}{L} (h - H_0) = 0 \quad \Delta h = h - H_0$$

$$\frac{d^2 \Delta h}{dt^2} + \underbrace{\left(\frac{d}{D}\right)^2 \frac{g}{L}}_k \Delta h = 0$$

Resolviendo la ecuación diferencial siguiente:

$$\Delta h + k \Delta h = 0$$

$$\Rightarrow \Delta h = A \operatorname{sen}(\sqrt{k} t) + B \operatorname{cos}(\sqrt{k} t)$$

Aplicando las condiciones de borde:

$$1) t = t_0 \quad \Delta h = \Delta h_0 = H_0 - H_d$$

$$2) \quad \Delta h = \frac{d\Delta h}{dt} = \frac{dh}{dt} - \frac{dH_0}{dt} = \frac{Q}{\frac{\pi D^2}{4}} = \sqrt{2g(H_0 - H_d)} \left(\frac{d}{D}\right)^2$$

$$\Delta h = H_d - H_d = A \operatorname{sen}(\sqrt{k} \cdot 0) + B \operatorname{cos}(\sqrt{k} \cdot 0) \Rightarrow \underline{H_0 - H_d = B}$$

$$\frac{d\Delta h}{dt} = A \operatorname{cos}(\sqrt{k} t) \sqrt{k} - B \operatorname{sen}(\sqrt{k} t) \sqrt{k}$$

$$\sqrt{2g(H_0 - H_d)} \left(\frac{d}{D}\right)^2 = A \sqrt{k}$$

$$\Rightarrow B = + \sqrt{2g(H_0 - H_d)} \left(\frac{d}{D}\right)^2 \cdot \frac{1}{\left(\frac{d}{D}\right) \sqrt{\frac{g}{L}}}$$

$$\therefore \Delta h = (H_0 - H_d) \operatorname{cos}(\sqrt{k} t) + \frac{\sqrt{2(H_0 - H_d)}}{\sqrt{L}} \left(\frac{d}{D}\right) \operatorname{sen}(\sqrt{k} t)$$

Werte:

$$H_0 = 50 \text{ m}$$

$$H_d = 5 \text{ m}$$

$$L = 40 \text{ m}$$

$$d = 40 \text{ cm}$$

$$D = 2 \text{ m}$$

$$k = \left(\frac{d}{D} \right)^2 \cdot \frac{g}{L} = 6,125 \times 10^{-4} \left[\frac{1}{s^2} \right]$$

$$\rightarrow \Delta h = 5 \cdot \cos(2,475 \times 10^{-2} t) + 0,025 \cdot \sin(2,475 \times 10^{-2} t) \quad |$$

c) $H_e = 7 \text{ m}$

$$\Delta h = H_0 - h = H_0 - H_e = 3 \text{ m} \quad \rightarrow t?$$

$$3 = 5 \cdot \cos(2,475 \times 10^{-2} t) + 0,025 \cdot \sin(2,475 \times 10^{-2} t)$$

$$\Rightarrow t_a = 12410,3 \text{ [s]} \quad | \quad \rightarrow 3,447 \text{ [hr]} \quad |$$