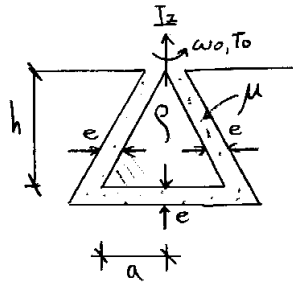


P1)



$\frac{1}{2}$

Se divide el problema en dos partes: manto y fondo

Fondo: (2 discos paralelos separados por un espesor e)

$$dT = r dF \quad ; \quad dF = \tau dA \quad ; \quad dA = r dr d\theta$$

$$\Rightarrow dT = r^2 \tau dr d\theta$$

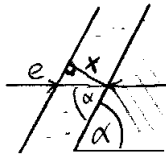
Ley de Newton-Navier: $\tau = \mu \frac{du}{dz} = \mu r \frac{\omega_0}{e}$

$$\Rightarrow dT = r^2 \frac{\mu \cdot r \cdot \omega_0}{e} dr d\theta$$

$$\int dT = \int_0^{2\pi} \int_0^a r^3 dr d\theta \cdot \frac{\mu \cdot \omega_0}{e}$$

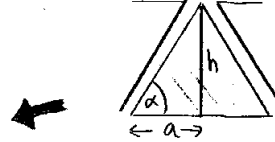
$$T_{\text{fondo}} = 2\pi \frac{a^4}{4} \cdot \frac{\mu \omega_0}{e} \Rightarrow \boxed{T_{\text{fondo}} = \frac{\pi a^4}{2} \cdot \frac{\mu \omega_0}{e}}$$

Manto:



$$\Rightarrow \sin \alpha = \frac{x}{e}$$

$$\sin \alpha = \frac{h}{\sqrt{a^2 + h^2}}$$



$$dT = r dF \quad ; \quad dF = \tau \cdot dA \quad ; \quad \tau = \mu r \frac{d\omega}{dr}$$

$$dT = r \tau dA \quad \text{con } dA = r d\theta dz$$

$$dT = r^2 \tau d\theta dz = \mu r^3 \frac{d\omega}{dr} d\theta dz$$

Notar que $\frac{r}{z} = \frac{a}{h} \Rightarrow dz = \frac{h}{a} dr$

$$\frac{d\omega}{dr} = \frac{\omega_0}{e \cdot \sin \alpha}$$

$$\int dT = \int_0^{2\pi} \int_0^a \frac{\mu h \omega_0}{a e \sin \alpha} r^3 d\theta dr$$

$$\begin{aligned} T_{\text{manto}} &= \frac{\mu \cdot h}{a} \frac{\omega_0}{e \cdot h} \sqrt{a^2 + h^2} \cdot 2\pi \cdot \frac{a^4}{4} \\ &= \frac{\mu \sqrt{a^2 + h^2} \cdot \pi a^3}{2e} \omega_0 \end{aligned}$$

$$\Rightarrow \text{Torque total} = T_{\text{fondo}} + T_{\text{manto}} = \omega_0 \cdot \frac{\pi \mu a^3}{2e} [a + \sqrt{a^2 + h^2}]$$

Evaluando con datos entregados:

2/2

$$T_{\text{total}} = \frac{2\pi [\text{rad/s}] \cdot \pi \cdot 0,007 \left[\frac{\text{kg}}{\text{m}^4 \text{s}} \right] \cdot 0,2^3 [\text{m}^3] \left[0,2 + \sqrt{0,2^2 + 0,3^2} \right] [\text{m}]}{2 \cdot 0,007 [\text{m}]}$$

$$T_{\text{total}} = 0,0443 [\text{N} \cdot \text{m}]$$

b) $\Sigma T_{\text{externas}} = I_z \frac{d\omega}{dt}$

Inicialmente $\Sigma T_{\text{externas}} = 0$, $\dot{\omega} = 0$, $\omega = \text{cte.}$

Cuando deja de aplicarse el torque antes calculado, $\frac{d\omega}{dt} < 0$, por el efecto de la viscosidad del liquido.

$$T_r = -\omega \frac{\pi \mu a^3}{2e} [a + \sqrt{a^2 + h^2}] = -\omega \cdot b \quad b = \text{cte.}$$

$$I_z = M \cdot \frac{3}{10} a^2 \quad M = \text{Vol}_{\text{cono}} \cdot \rho$$

$$= \frac{\pi a^2 h}{3} \cdot \rho$$

$$I_z = \frac{\pi}{10} a^4 h \cdot \rho$$

$$\text{Evaluando: } b = \frac{\pi \mu a^3}{2e} [a + \sqrt{a^2 + h^2}] = 0,00704 \left[\frac{\text{kg} \cdot \text{m}^2}{\text{s}} \right]$$

$$I_z = 0,1206 [\text{kg} \cdot \text{m}^2]$$

$$-\omega \cdot b = I_z \cdot \frac{d\omega}{dt}$$

$$\text{separando variables: } -b dt = I_z \frac{d\omega}{\omega}$$

$$\begin{matrix} t=0 & \omega = \omega_0 \\ t=t^* & \omega = \omega_0/2 \end{matrix}$$

$$-b \int_0^{t^*} dt = I_z \int_{\omega_0}^{\omega_0/2} \frac{d\omega}{\omega}$$

$$-b t^* = I_z \left[\ln \frac{\omega_0}{2} - \ln \omega_0 \right]$$

$$t^* = -\frac{I_z}{b} \ln \left(\frac{1}{2} \right) = \frac{I_z}{b} \ln 2$$

$$\Rightarrow t^* = 11,87 [\text{seg}]$$