

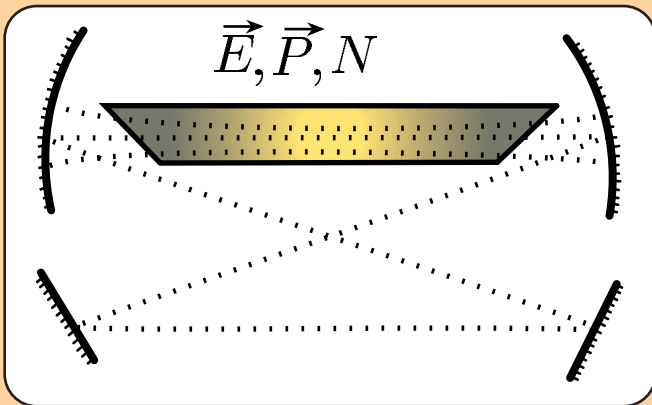
Mechanical analog of a
laser close to the 1:1
resonance

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Outline

- Introduction to the laser Physics.
- Laser Instability.
- Hamiltonian bifurcation and quasi-reversible instability.
- Examples of 1:1 Resonances
- Mechanical analog of the laser
- Latent Bifurcation.
- Conclusion.

Semiclassical Laser Model



$$\begin{aligned}\frac{\partial^2 E}{\partial t^2} &= \frac{\partial^2 E}{\partial x^2} - \frac{\partial^2 P}{\partial t^2} - \kappa \frac{\partial E}{\partial t}, \\ \frac{\partial^2 P}{\partial t^2} &= -\gamma_{\perp} \frac{\partial P}{\partial t} - (\gamma_{\perp}^2 + \Omega^2)P - \mu^2 NE, \\ \frac{\partial N}{\partial t} &= -\gamma_{\parallel}(N - N_0) + E \left(\frac{\partial P}{\partial t} + \gamma_{\perp} P \right),\end{aligned}$$

where the terms proportional to κ , γ_{\perp} and γ_{\parallel} are dissipatives.

The nonlasing solution (equilibrium) is

$$E = P = 0 \text{ and } N = D_0$$

Non dissipative semiclassical model

$$\begin{aligned}\frac{\partial^2 E}{\partial t^2} &= \frac{\partial^2 E}{\partial x^2} - \left(\frac{\mu}{\Omega}\right)^2 \frac{\partial^2 P}{\partial t^2}, \\ \frac{\partial P}{\partial t} &= G, \quad \frac{\partial G}{\partial t} = -P - NE, \\ \frac{\partial N}{\partial t} &= EG.\end{aligned}$$

where $P \rightarrow \mu/\Omega P$, $E \rightarrow \Omega/\mu E$, $t \rightarrow t/\Omega$, $x \rightarrow x/\Omega$

This model has Hamiltonian density

$$\mathcal{H} = \frac{1}{2} \left(D - \left(\frac{\mu}{\Omega}\right)^2 P \right)^2 + \frac{(\partial_x A)^2}{2} + \left(\frac{\mu}{\Omega}\right)^2 N,$$

with $E = \partial_t A = D - (\mu/\Omega)^2 P$.

and the Poisson-bracket

$$\{F, K\} = \int dx \left\{ \frac{\partial F}{\partial A} \frac{\partial K}{\partial D} - \frac{\partial F}{\partial D} \frac{\partial K}{\partial A} - \left(\frac{\mu}{\Omega}\right)^2 \vec{m} \cdot (\vec{\nabla}_m F \times \vec{\nabla}_m K) \right\},$$

where $\vec{m} = (N, P, G)$

Energie-Casimir Method

- $\{\Phi(N^2 + P^2 + G^2), F\} = 0$
- The effective energie

$$\begin{aligned}H_C &= \int \left\{ \frac{1}{2} \left(D - \left(\frac{\mu}{\Omega}\right)^2 P \right)^2 + \frac{(\partial_x A)^2}{2} + \left(\frac{\mu}{\Omega}\right)^2 N + \right. \\ &\quad \left. \left(\frac{\mu}{\Omega}\right)^2 \frac{(N^2 + P^2 + G^2)}{2D_o} + \alpha^2 (N^2 + P^2 + G^2)^2 \right\},\end{aligned}$$

Reversible and Hamiltonian systems

$$\partial_t u = f(u), \quad \partial_t S u = -f(S u), \quad S^2 = 1$$

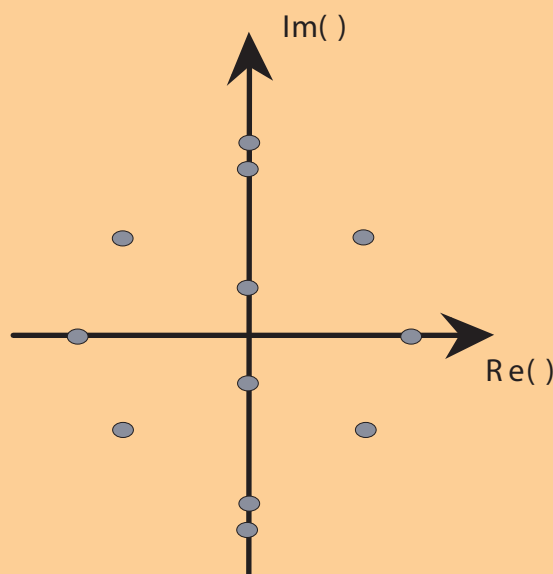
$$t \longrightarrow -t, \quad u \longrightarrow S u$$

- Example : Hamiltonian Systems

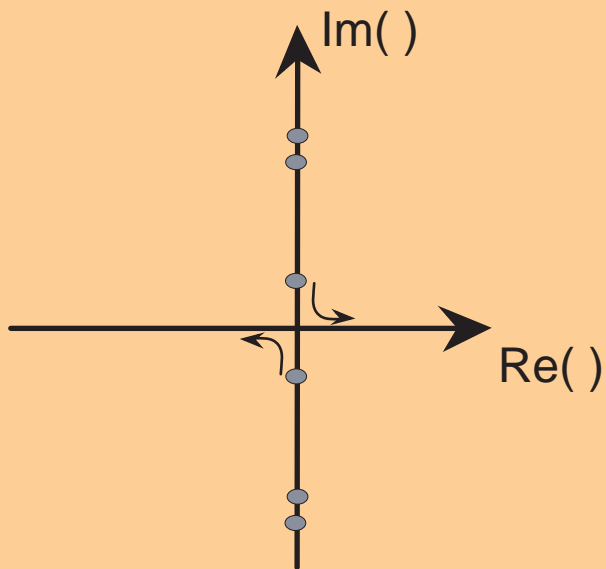
$$H(\vec{p}, \vec{q}) = \sum_{i=1}^n \frac{p_i p_i}{2} + V(\vec{q})$$

$$t \rightarrow -t, \quad \vec{q}^i \rightarrow \vec{q}^i, \quad \vec{p}_i \rightarrow -\vec{p}_i, \quad i = 1, \dots, n$$

- instabilities ($\lambda \longrightarrow -\lambda$, for reversal solution)

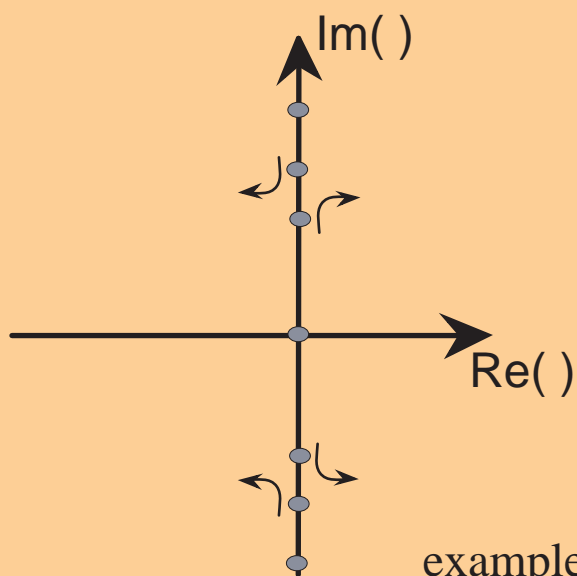


i) Stationary instability



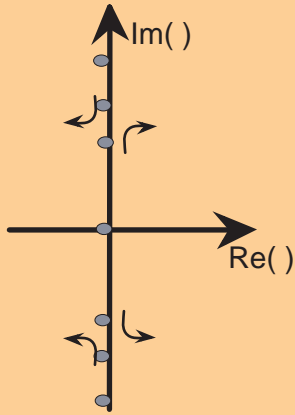
example : rotating pendulum

ii) Confusion of frequencies (Rocard ('43))



example : wing's aircraft,
Laser

- In the quasi-reversible confusion of frequencies, the asymptotic normal form



$$A_{tt} = \epsilon A - (\nu + i\Delta) A_t - |A|^2 A - zA$$

$$z_t = -\mu z + \eta |A|^2$$

- J. Gibbon et al ('80): the dispersive instability with small dissipation.

Introducing the change of variables

$$P = \kappa E + \partial_t E, \quad E = e^{-i \frac{\Delta \kappa}{\gamma + \kappa} t} \frac{A}{\sqrt{g}}, \quad N = \frac{z - D_o}{g} + |E|^2,$$

the equations read (Maxwell-Bloch or complex Lorenz eqs.)

$$\partial_t E = -\kappa E + P$$

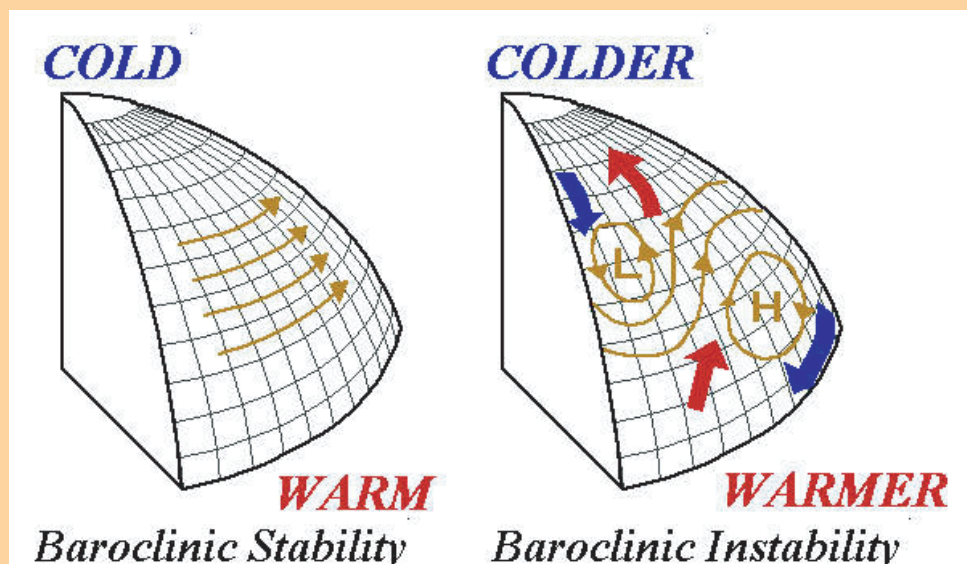
$$\partial_t P = -(\gamma_{\perp} + i\Delta)P - gNE$$

$$\partial_t N = -\gamma_{\parallel}(N - N_0) + (E\bar{P} + \bar{E}P)$$

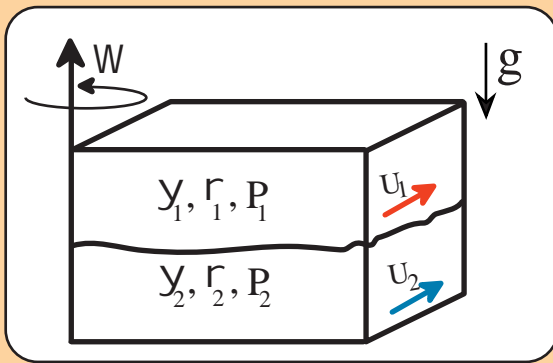
Physical examples

Baroclinic instability

This instability gives rise waves motion due to vertical shear of the basic current in the presence of Coriolis and buoyancy forces



Quasi-Geostrophic Two-layer Model



two layers of immiscible, incompressible, homogeneous fluid of slightly different densities ($\rho_2 > \rho_1$). The dimensionless quasi-geostrophic vorticity equations are

$$\begin{aligned} [\partial_t + \psi_{1,x} \partial_y - \psi_{1,y} \partial_x] \left[\vec{\nabla}^2 \psi_1 + F(\psi_2 - \psi_1) + \beta y \right] &= -r \vec{\nabla}^2 \psi_1, \\ [\partial_t + \psi_{2,x} \partial_y - \psi_{2,y} \partial_x] \left[\vec{\nabla}^2 \psi_2 + F(\psi_1 - \psi_2) + \beta y \right] &= -r \vec{\nabla}^2 \psi_2, \end{aligned}$$

- This system is Lagrangean

$$\mathcal{L} = \int \frac{1}{2} (\vec{\nabla} \psi_1)^2 + \frac{1}{2} (\vec{\nabla} \psi_2)^2 + \frac{F}{2} (\psi_1 - \psi_2)^2 - \beta y (\psi_1 + \psi_2) dt dx dy,$$

constrained to Euler-Poincaré variations

$$\begin{aligned} \delta \psi_1 &= \frac{\partial}{\partial t} \delta \phi_1 + \hat{z} \cdot (\vec{\nabla} \psi_1 \times \vec{\nabla} \delta \phi_1), \\ \delta \psi_2 &= \frac{\partial}{\partial t} \delta \phi_2 + \hat{z} \cdot (\vec{\nabla} \psi_2 \times \vec{\nabla} \delta \phi_2). \end{aligned}$$

Where the stream functions depend of the horizontal coordinate and time. The respective Hamiltonian is

$$\mathcal{H} = \int \frac{1}{2} (\vec{\nabla} \psi_1)^2 + \frac{1}{2} (\vec{\nabla} \psi_2)^2 + \frac{F}{2} (\psi_1^2 + \psi_2^2) dx dy,$$

If one considers perturbations of the geostrophic basic flow of the form

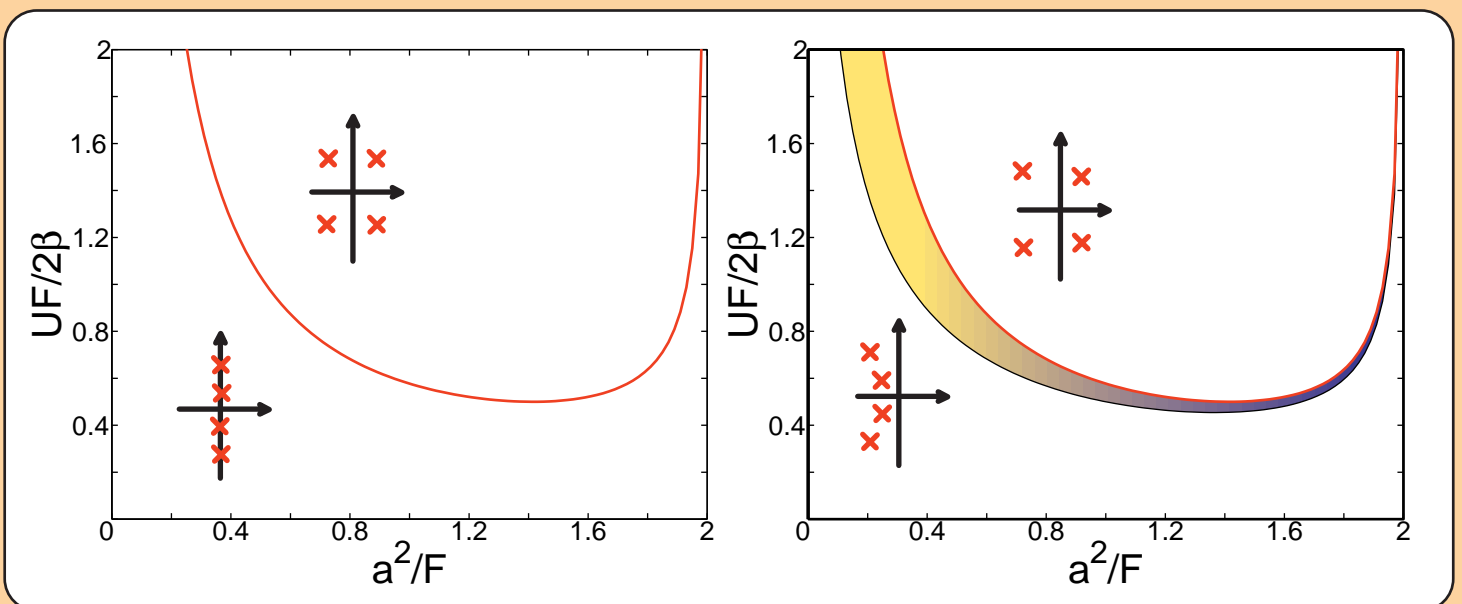
$$\begin{aligned}\psi_1 &= -U_1 y + \operatorname{Re} A e^{i\alpha(x-ct)} \sin(m\pi y), \\ \psi_2 &= -U_2 y + \operatorname{Re} \gamma A e^{i\alpha(x-ct)} \sin(m\pi y),\end{aligned}$$

then dispersion relation is

$$\begin{aligned}c &= \frac{U_1 + U_2}{2} - \frac{a^2 + F}{a^2 + 2F} \left[\frac{\beta + i\alpha r}{\alpha^2} \right] \\ &\pm \frac{\left[(\Delta U)^2 a^4 (a^4 - 4F^2) + 4F^2 (\beta + i r a^2 \alpha^{-1}) \right]^{1/2}}{2a^2 (a^2 + 2F)}\end{aligned}$$

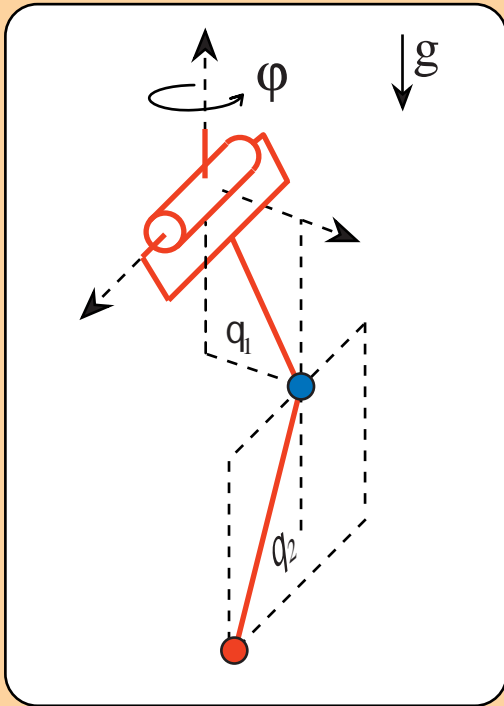
where $a^2 = \alpha^2 + m^2\pi^2$ and $\Delta U \equiv U_1 - U_2$.

● Bifurcation diagram for small viscosity

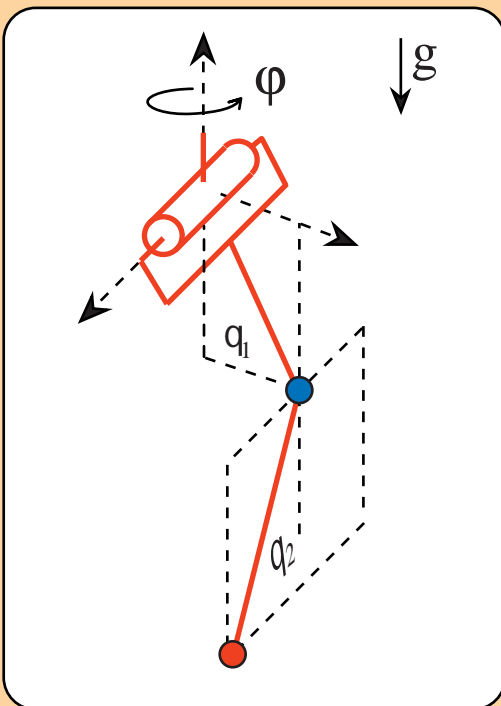


● references(E.O. Holopainen 1961, Romea 1977).

Mechanical Laser



Two coupled spherical pendula in a gravitational field, with a support, which can rotate around the vertical axis. The lower pendulum is constrained to move in a plane that is orthogonal to the plane of the upper pendulum.

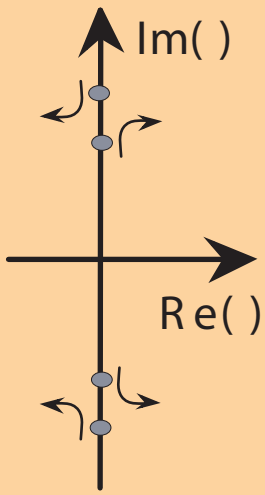


$$\begin{aligned} \ddot{\theta}_1 = & -\sigma^2 \sin \theta_1 \sin \theta_2 \ddot{\theta}_2 - \sigma^2 \sin \theta_1 \cos \theta_2 \dot{\theta}_2^2 \\ & -2\sigma^2 \cos \theta_1 \cos \theta_2 \dot{\varphi} \dot{\theta}_2 + \sin \theta_1 \cos \theta_1 \dot{\varphi}^2 \\ & -\sigma^2 \cos \theta_1 \sin \theta_2 \ddot{\varphi} - \frac{g}{l} \sin \theta_1 - \nu_1 \dot{\theta}_1, \end{aligned}$$

$$\begin{aligned} \ddot{\theta}_2 = & -\sin \theta_1 \sin \theta_2 \ddot{\theta}_1 - \cos \theta_1 \sin \theta_2 \dot{\theta}_1^2 \\ & +2 \cos \theta_1 \cos \theta_2 \dot{\varphi} \dot{\theta}_1 + \sin \theta_2 \cos \theta_2 \dot{\varphi}^2 \\ & + \sin \theta_1 \cos \theta_2 \ddot{\varphi} - \frac{g}{l} \sin \theta_2 - \nu_2 \dot{\theta}_2, \end{aligned}$$

$$\frac{d}{dt} \left\{ \begin{array}{l} (\sin^2 \theta_1 + \sigma^2 \sin^2 \theta_2) \dot{\varphi} + \sigma^2 \cos \theta_1 \sin \theta_2 \dot{\theta}_1 \\ -\sigma^2 \sin \theta_1 \cos \theta_2 \dot{\theta}_2 + I \dot{\varphi} \end{array} \right\} = -\nu_\varphi (\dot{\varphi} - \Omega) - \mu_1 \sin^2 \theta_1 \dot{\varphi} - \mu_2 (\sin^2 \theta_1 + \sin^2 \theta_2) \dot{\varphi}.$$

where $l_1 = l_2 = l$ and $\sigma = \sqrt{m_2 / (m_1 + m_2)}$



The vertical solution

$$\theta_1 = \theta_2 = 0, \varphi_t = \Omega_0$$

exhibits a 1:1 resonance when

$$\Omega_0 = \Omega_c = \sqrt{\frac{g(m_1 + m_2)}{l m_1}}$$

with $\omega_c = \pm \sqrt{gm_2/lm_1}$ frequencies. The system is described by

$$A_{tt} = \frac{2g(\Omega - \Omega_c)}{l\Omega} A + i(2\sigma(\Omega - \Omega_c)) A_t$$

● Quasi-reversible instability

$$\begin{aligned} \partial_{tt} A &= (\varepsilon - Z) A - (\mu - i\delta) \partial_t A - \alpha |A|^2 A \\ \partial_t Z &= \nu Z + \eta |A|^2. \end{aligned}$$

where

$$\begin{aligned} \varepsilon &= 2\frac{g}{l} \frac{(\Omega - \Omega_c)}{\Omega_c}, \quad \alpha = \frac{g}{4l} \left(\frac{\sigma^4 - 2\sigma^3 - 2\sigma^2 + 3}{1 - \sigma^2} \right), \\ \delta &= 2\sigma(\Omega - \Omega_c), \quad \nu = \frac{\nu_\varphi}{I}, \quad \mu = \frac{1}{2l^2} (\nu_1 + \nu_2), \\ \eta &= \frac{1}{I} \left[\mu_1 + \left(1 + \frac{1}{\sigma^2} \right) \mu_2 - 2\frac{\nu_\varphi}{\sigma^2 I} \left(\frac{\Omega}{\Omega_c} - 1 \right) \right]; \end{aligned}$$

FOUCAULT PENDULUM



- As consequence of Earth rotation, the vertical solution exhibits a latent bifurcation!

$$\ddot{x} = - \left(\frac{g}{l} - \Omega^2 \right) x + 2\Omega\dot{y}$$

$$\ddot{y} = - \left(\frac{g}{l} - \Omega^2 \right) y - 2\Omega\dot{x}$$

- Latent bifurcation.

- Dissipation induced instability.

- Applications : simple mechanical system, Laser, restricted three-body problem, Foucault pendulum, Chemical systems, nuclear physics and Baroclinic instability.

